MA2

series

Product Segments

- **Industrial Motion**

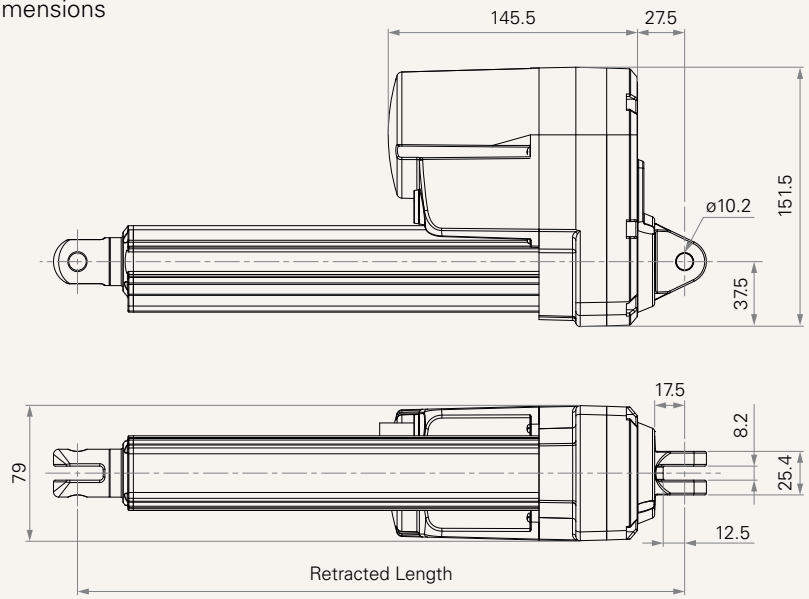
TiMOTION's MA2 series electric linear actuator was specifically designed for applications that face harsh working environments and require heavy-duty and durability. Its IP69K protection ensures it will withstand high-pressure water jets and the ingress of dust and other solid contaminants. The MA2 electric cylinder actuator also has optional Reed switches along the outer tube which allow users to adjust the stroke length. For improved control and accuracy of motion, the MA2 can be customized with many different feedback options depending on your application requirements. Example applications suitable for the MA2: Agricultural equipment such as spreaders, harvesters, grain handlers, combines, and tractors. Commercial and industrial applications such as commercial lawn mowers, scrubbers and sweepers, material handling equipment and livestock ventilation systems.

General Features

Max. load	8,000N (push); 4,000N (pull)
Max. speed at max. load	5.5mm/s
Max. speed at no load	52.5mm/s
Retracted length	≥ Stroke + 131mm
IP rating	IP69K
Certificate	UL73, EMC
Stroke	25~1000mm
Output Signals	Hall sensors, POT, Reed sensor on the outer tube
Voltage	12 / 24 / 36 / 48V DC; 12 / 24 / 36 / 48V DC (thermal control)
Operational temperature range	-30˚C~+65˚C
Operational temperature range at full performance	+5˚C~+45˚C
Manual drive	

Drawing

Standard Dimensions (mm)



Load and Speed

CODE	Load (N)		Self Lock (N)	Duty Cycle	Typical Current (A)		Typical Speed (mm/s)	
	Push	Pull	Motor brake		No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Speed (5200RPM)								
F	1000	1000	1300	25%	2.7	6.8	52.5	44.2
G	2000	2000	2600	25%	2.4	6.7	25.5	21.8
H	4000	4000	5200	25%	2.3	6.9	13.2	11.0
J	6000	4000	8000	25%	2.0	5.8	6.6	5.8
K	8000	4000	8000	15%	2.0	6.9	6.6	5.5

Note

1 Please refer to the approved drawing for the final authentic value.

2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.

3 The current & speed in table are tested with 24V DC motor. With a 12V DC motor, the current is approximately twice the current measured in 24V DC. With a 36V DC motor, the current is approximately two-thirds the current measured in 24V DC. Speed will be similar for all the voltages.

4 The current & speed in table are tested when the actuator is extending under push load.

5 The current & speed in table and diagram are tested with a stable 24V DC power supply.

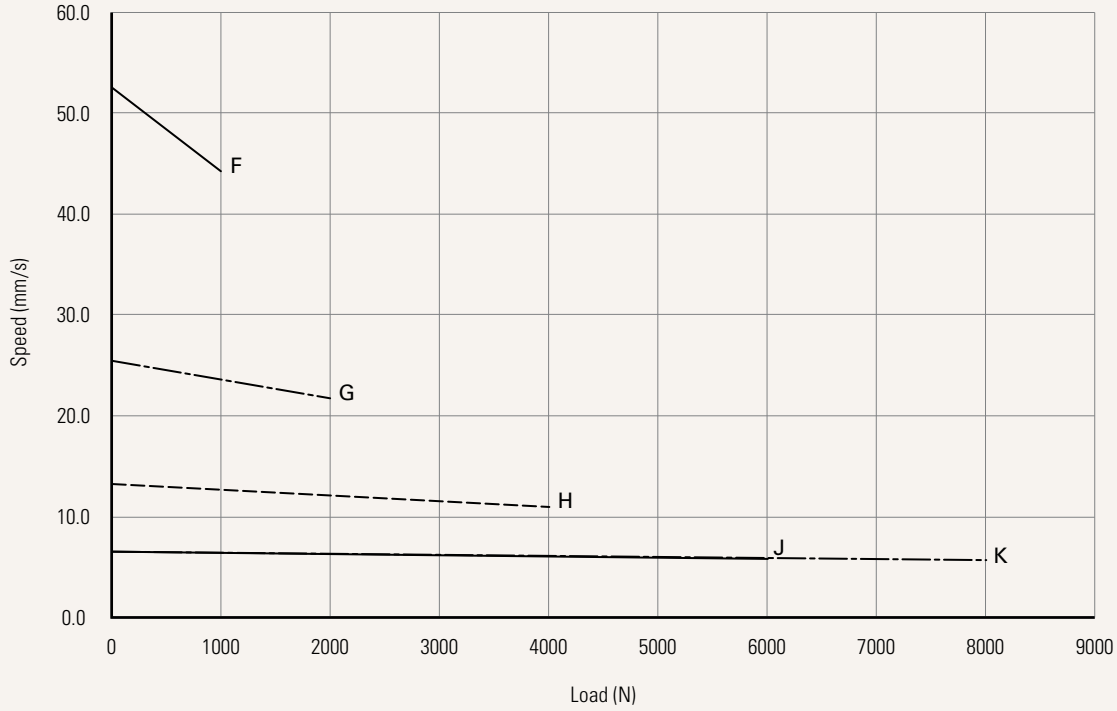
6 Standard stroke: Min. ≥ 25mm, Max. please refer to below table.

CODE	Load (N)	Max Stroke (mm)
F	≤ 1000	1000
G	≤ 2000	800
H, J	≤ 6000	600
K	≤ 8000	200

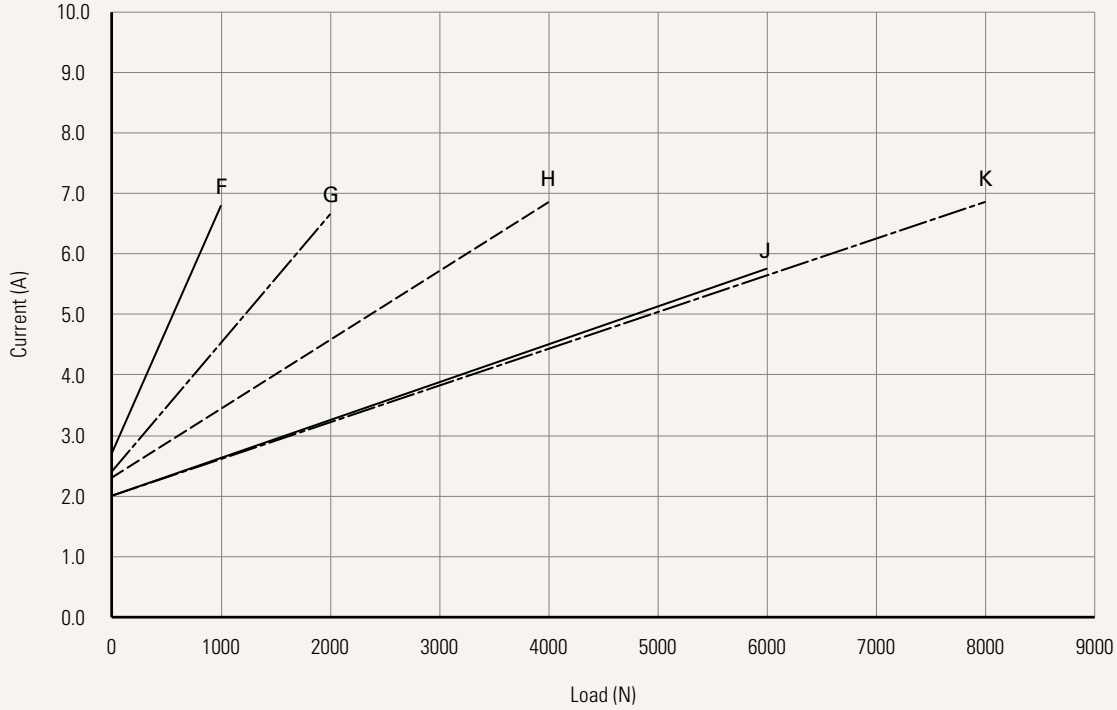
Performance Data (24V DC Motor)

Motor Speed (5200RPM)

Speed vs. Load



Current vs. Load



MA2 Ordering Key

MA2

Version: 20220415-I

Voltage	1 = 12V DC 2 = 24V DC 3 = 36V DC 4 = 48V DC		5 = 24VDC, thermal protector 6 = 12VDC, thermal protector 7 = 36VDC, thermal protector 8 = 48V DC, thermal cutoff	
Load and Speed	See page 2			
Stroke (mm)	See page 2			
Retracted Length (mm)	See page 5			
Rear Attachment (mm) See page 6	1 = Aluminum casting, clevis U, slot 8.2, depth 12.5, hole 10.2 2 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 10.2 3 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.8 4 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.2			
Front Attachment (mm) See page 6	1 = Iron inner tube with punched hole, without slot, hole 10.2 2 = Iron inner tube with punched hole, without slot, hole 12.2 3 = Iron inner tube with punched hole, without slot, hole 12.8 4 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 10.2 5 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.2 6 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.8 K = Rod end bearing, hole 12.8			
Direction of Installation (Counterclockwise) See page 7	1 = 90°	2 = 0°		
Functions for Limit Switches	1 = Two switches at full retracted / extended positions to cut current 2 = Two switches at full retracted / extended positions to cut current + third one in between to send signal 3 = Two switches at full retracted / extended positions to send signal 6 = Two switches at full retracted / extended positions to cut current + send signal			
Reed Sensor on the Outer Ttube	0 = Without	1 = Reed sensor*1	2 = Reed sensor*2	
Output Signal	0 = Without	1 = POT	5 = Hall sensor*2	
Connector See page 7	2 = Tinned leads			
Cable Length (mm)	1 = Straight, 500	2 = Straight, 1000	3 = Straight, 1500	4 = Straight, 2000
IP Rating	1 = Without 2 = IP54	3 = IP66 6 = IP66D	8 = IP69K	
Manual Drive	1 = With			
T-Smart	0 = Without			

MA2 Ordering Key Appendix

Retracted Length (mm)

1. Calculate A+B+C = Y
2. Retracted length needs to ≥ Stroke + Y

A. Rear/ Front Attachment		
Front Attachment	Rear Attachment	
	1	2, 3, 4
1, 2, 3	+131	+134
4, 5, 6	+161	+164
K	+178	+181

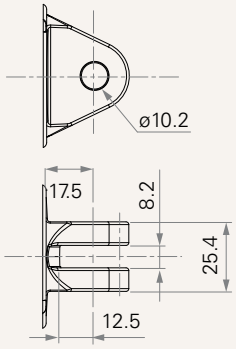
C. Output Signal	
0, 5	-
1	+20

B. Stroke (mm)	
25~150	-
151~200	-
201~250	+10
251~300	+20
301~350	+30
351~400	+40
401~450	+50
451~500	+60
501~550	+70
551~600	+80
601~650	+90
651~700	+100
701~750	+110
751~800	+120
801~850	+130
851~900	+140
901~950	+155
951~1000	+160

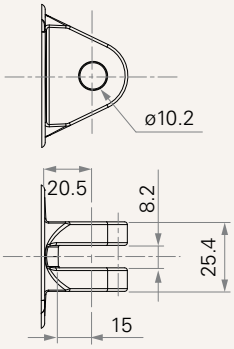
MA2 Ordering Key Appendix

Rear Attachment (mm)

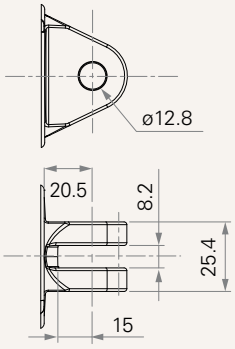
1 = Aluminum casting, clevis U, slot 8.2, depth 12.5, hole 10.2



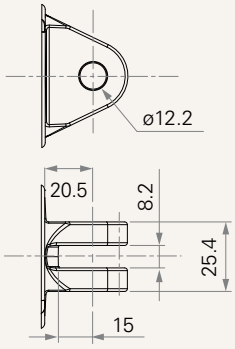
2 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 10.2



3 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.8

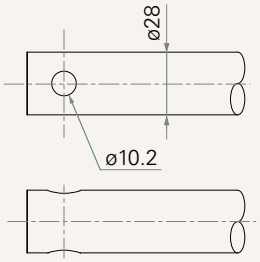


4 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.2

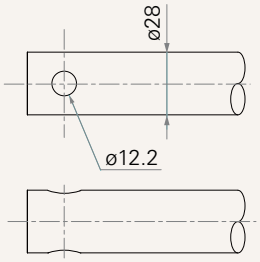


Front Attachment (mm)

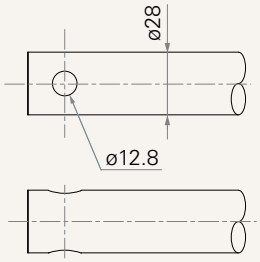
1 = Iron inner tube with punched hole, without slot, hole 10.2



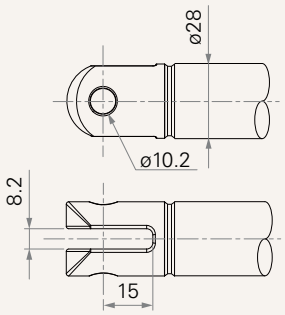
2 = Iron inner tube with punched hole, without slot, hole 12.2



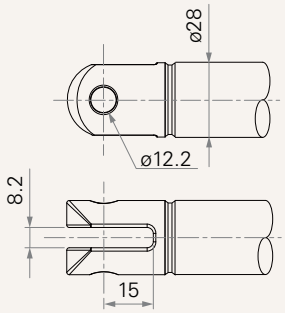
3 = Iron inner tube with punched hole, without slot, hole 12.8



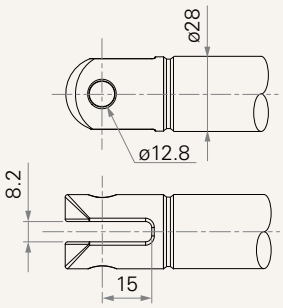
4 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 10.2



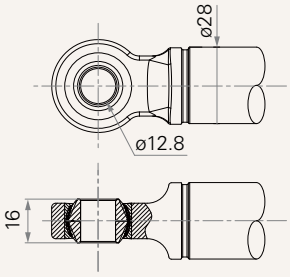
5 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.2



6 = Aluminum casting, clevis U, slot 8.2, depth 15.0, hole 12.8

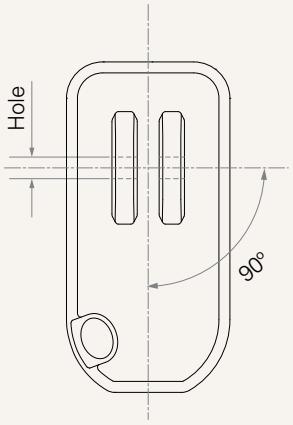


K = Rod end bearing, hole 12.8

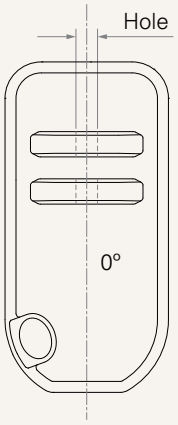


Direction of Rear Attachment (Counterclockwise)

1 = 90°

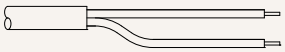


2 = 0°



Connector

2 = Tinned leads



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