JP4

series

Product Segments

- **Industrial Motion**

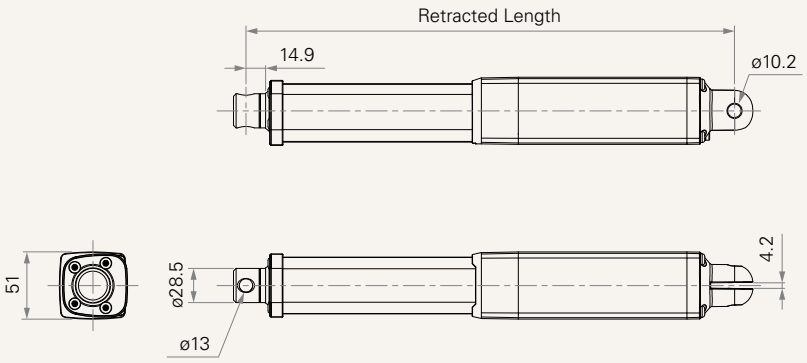
TiMOTION's JP4 series inline linear actuator is most similar to the JP3, but was designed for industrial applications that require higher load and speed. Its IP69K (static) protection ensures it will withstand high temperature, high pressure water jets, and the ingress of dust and other solid contaminants. For synchronization and position feedback, the JP4 can be equipped with Hall sensors.

General Features

Max. load	4,500N (push); 3,000N (pull)
Max. speed at max. load	2.5mm/s
Max. speed at no load	27.5mm/s
Retracted length	≥ Stroke + 289mm
IP rating	IP69K (static)
Certificate	UL73
Stroke	20~1000mm
Output signals	NPN Hall sensors (5~36V input) * 2
Voltage	12/24V DC; 12/24V DC (PTC)
Color	Black, grey
Operational temperature range	-5°C~+65°C
Operational temperature range at full performance	+5°C~+45°C
Storage temperature range	-40°C~+70°C

Drawing

Standard Dimensions
(mm)



Load and Speed

CODE	Load (N)		Self Locking Force (N)	Typical Current (A)		Typical Speed (mm/s)		Typical Current (A)		Typical Speed (mm/s)	
	Push	Pull		No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC	No Load 12V DC	With Load 12V DC	No Load 12V DC	With Load 12V DC
Motor Speed (3800RPM, Duty Cycle 10%)											
B	4500	3000	4500	1.5	4.0	4.4	2.5	2.8	8.0	4.4	2.5
C	3500	3000	3000	1.5	4.0	6.5	4.0	2.8	8.0	6.5	4.0
D	2500	2500	2000	1.5	4.0	9.2	5.6	2.8	8.0	9.2	5.6
E	1500	1500	1000	1.5	3.0	12.0	9.5	2.8	6.0	12.0	9.5
F	1000	1000	700	1.5	3.0	18.0	14.0	2.8	6.0	18.0	14.0
G	500	500	500	1.5	3.0	27.5	24.0	2.8	6.0	27.5	24.0

Note

1 Please refer to the approved drawing for the final authentic value.

2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.

3 The current & speed in table are tested with 24V DC motor. With a 12V DC motor, the current is approximately twice the current measured in 24V DC; speed will be similar for both voltages.

4 The current & speed in table are tested when the actuator is extending under push load.

5 The current & speed in table and diagram are tested with a stable 24V DC power supply.

6 Without load, noise level ≤ 60dBA (by TiMOTION test standard, ambient noise level ≤ 36dBA)

7 Standard stroke: Min. ≥ 20mm, Max. please refer to the table below

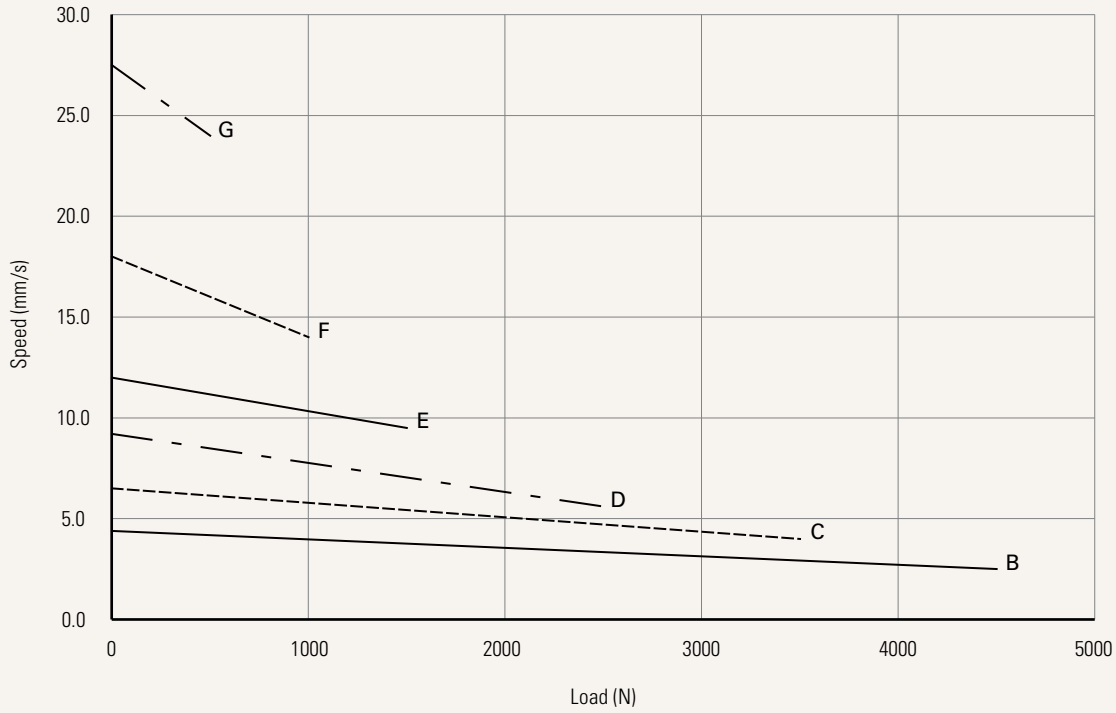
8 Tolerance: fully extended length & retracted length ±3mm

CODE	Load (N)	Max Stroke (mm)
B	4500	400
C	3500	500
D	2500	600
E	1500	700
F	1000	800
G	500	1000

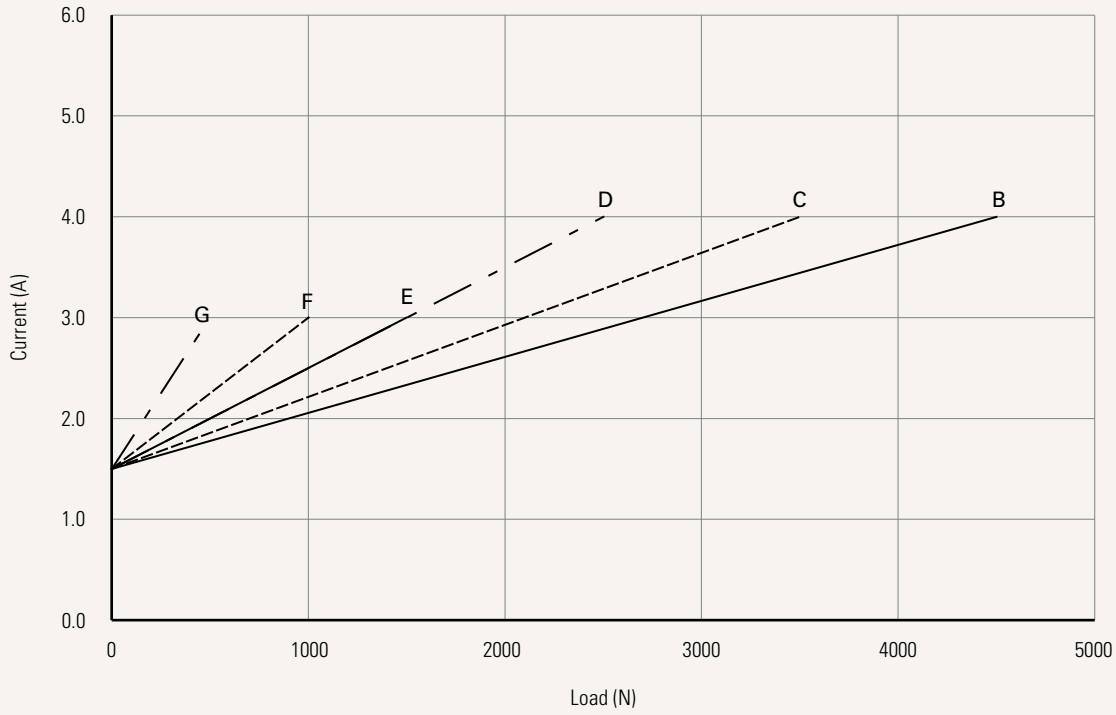
Performance Data (24V DC Motor)

Motor Speed (3800RPM, Duty Cycle 10%)

Speed vs. Load



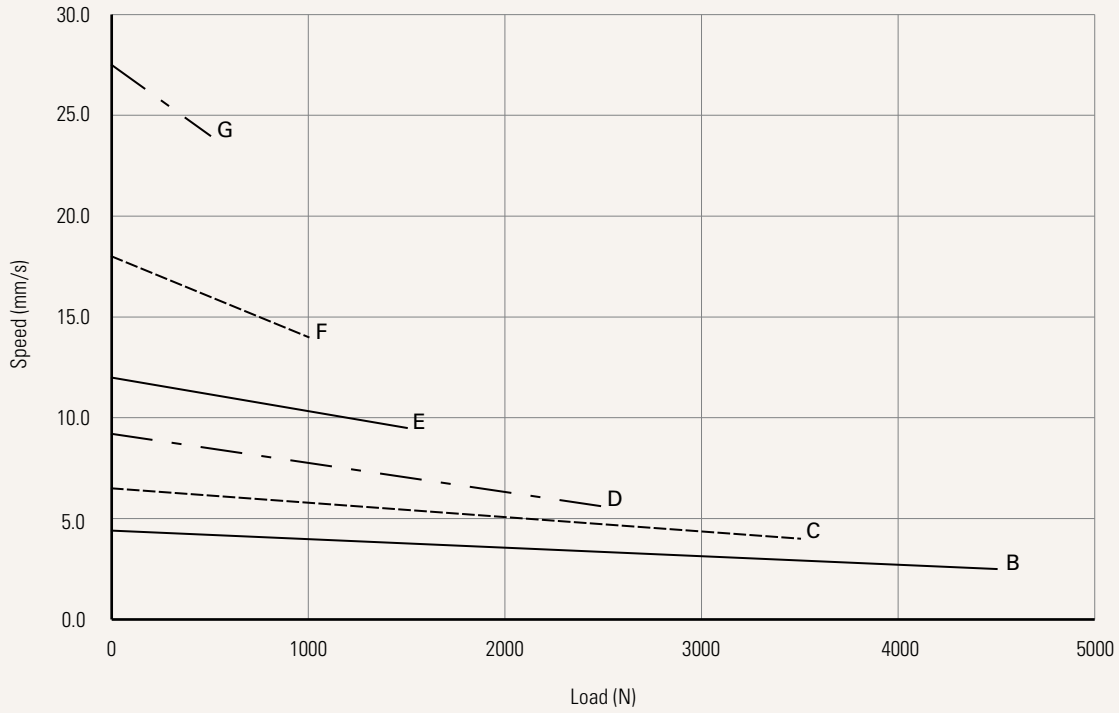
Current vs. Load



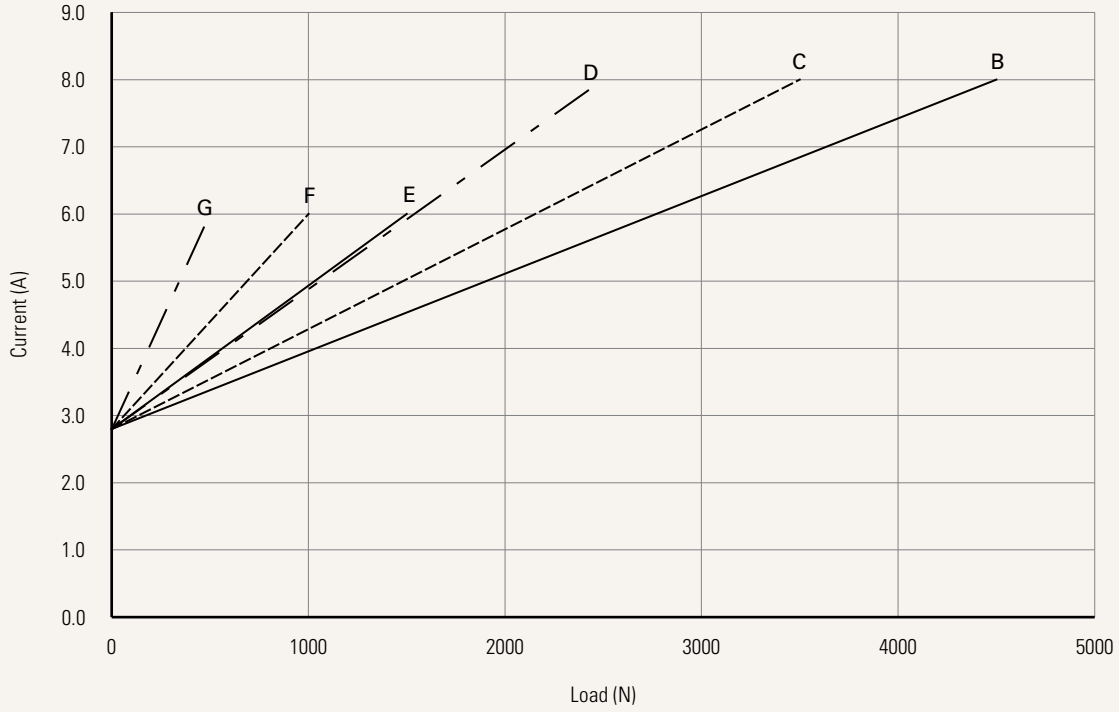
Performance Data (12V DC Motor)

Motor Speed (3800RPM, Duty Cycle 10%)

Speed vs. Load



Current vs. Load



JP4 Ordering Key

JP4

Version: 20251204-L

Voltage See page 8	1 = 12V DC	2 = 24V DC	5 = 24V DC, PTC	6 = 12V DC, PTC
Load and Speed	See page 2			
Stroke (mm)	See page 2			
Retracted Length (mm)	See page 6			
Rear Attachment (mm) See page 7	1 = Aluminum, U clevis, slot 4.2, depth 18.0, hole 10.2			
Front Attachment (mm) See page 7	1 = Aluminum, slotless, hole 13.0			
Direction of Rear Attachment (Counterclockwise) See page 7	1 = 0°			
Color	1 = Black	2 = Pantone 428C		
IP Rating	1 = Without 2 = IP54	3 = IP66 6 = IP66M	7 = IP68 8 = IP69K	9 = IP66M / IP68 / IP69K + Reinforced
Special Function of Spindle Subassembly	0 = Without (Standard)			
Function of Limit Switches See page 9	1 = Two micro switches cut off the actuator at end of stroke 2 = Two micro switches cut off the actuator at end of stroke + third one in between sends signal 3 = Two micro switches send signal at end of stroke 4 = Two micro switches send signal at end of stroke + third one in between sends signal			
Output Signal See page 9	0 = Without		N = NPN Hall sensor (5-36V input) * 2	
Connector See page 8	1 = DIN 6P, 90° plug	2 = Tinned leads		
Cable Length (mm)	0 = Straight, 100	1 = Straight, 500	3 = Straight, 1000	

JP4 Ordering Key Appendix

Retracted Length (mm)

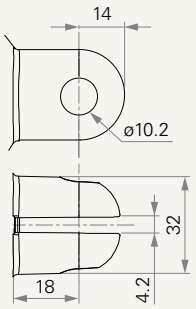
1. Calculate A+B = Y
2. Retracted length needs to ≥ Stroke + Y

A. Rear Attachment	
1	+289

B. Stroke (mm)	
20~150	-
151~200	-
201~250	+10
251~300	+20
301~350	+30
351~400	+40
401~450	+50
451~500	+60
501~550	+70
551~600	+80
601~650	+90
651~700	+100
701~750	+110
751~800	+120
801~850	+130
851~900	+140
901~950	+150
951~1000	+160

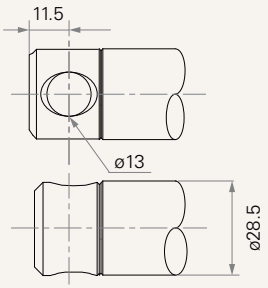
Rear Attachment (mm)

1 = Aluminum, U clevis, slot 4.2,
depth 18.0, hole 10.2



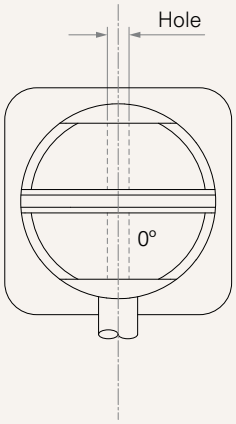
Front Attachment (mm)

1 = Aluminum, slotless, hole 13.0



Direction of Rear Attachment (Counterclockwise)

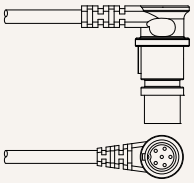
1 = 0°



JP4 Ordering Key Appendix

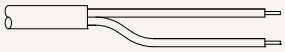
Connector

1 = DIN 6P, 90° plug



Connector IP = IP66

2 = Tinned leads

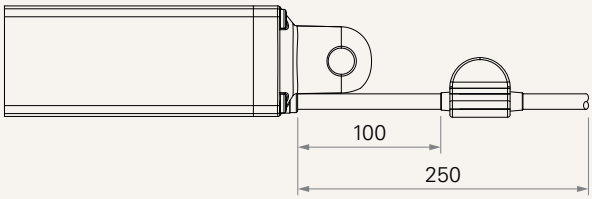


Connector IP = Without IP

Voltage

5 = 24V DC, PTC

6 = 12V DC, PTC



PTC outside the motor; at cable length 100mm,
min total cable = 250mm

JP4 Ordering Key Appendix

Wire Definition

Port Number	Functions for Limit Switches	Wire Color	Wire Gauge (AWG)	Position Feedback		
				0. Without	1. Hall Sensor*1	2,N. Hall Sensor*2
A1	1. Two micro switches cut off the actuator at end of stroke	GR	20	EXT+	EXT+	EXT+
		YE	20	RET+	RET+	RET+
		RE	26	-	Vcc	Vcc
		WH	26	-	S1	S1
		BK	26	-	GND	GND
		BU	26	-	-	S2
A1	2. Two micro switches cut off the actuator at end of stroke + third one in between sends signal	GR	20	EXT+	-	-
		YE	20	RET+	-	-
		RE	26	-	-	-
		WH	26	COM	-	-
		BK	26	MD LS (N.C.)	-	-
		BU	26	-	-	-
A1	3. Two micro switches send signal at end of stroke	GR	20	EXT+	-	-
		YE	20	RET+	-	-
		RE	26	COM	-	-
		WH	26	UP LS (N.C.)	-	-
		BK	26	-	-	-
		BU	26	LOW LS (N.C.)	-	-
A1	4. Two micro switches send signal at end of stroke + third one in between sends signal	GR	20	EXT+	-	-
		YE	20	RET+	-	-
		RE	26	COM	-	-
		WH	26	UP LS (N.C.)	-	-
		BK	26	MD LS (N.C.)	-	-
		BU	26	LOW LS (N.C.)	-	-

Terms of Use

The user is responsible for determining the suitability of TiMOTION products for a specific application.
TiMOTION products are subject to change without prior notice.