

TA51

series



Product Segments

- **Care Motion**

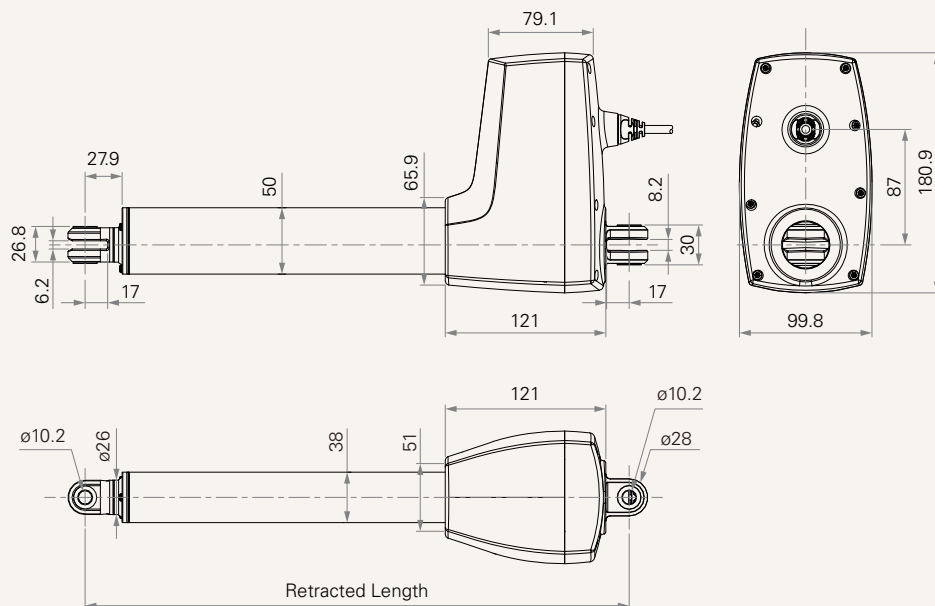
The TA51 is a high-performance medical electric linear actuator engineered for strength and reliability. With a powerful lifting capacity of up to 10,000N and an IP rating of up to IP66W, it is built to withstand demanding medical environments. Designed for versatility, the TA51 is ideal for operating beds and high-load patient lifting systems, delivering the precision and durability essential for critical medical applications.

General Features

Max. load	10,000N (push); 6,000N (pull)
Max. speed at max. load	5.7mm/s
Max. speed at no load	14.7mm/s
Retracted length	≥ Stroke + 190mm
IP rating	IP66W
Certificate	IEC60601-1, ES60601-1, IEC60601-1-2
Stroke	25~450mm
Output signals	Hall sensors, POT
Options	Manual release (for patient hoist)
Voltage	24V DC; 24V DC (PTC)
Color	Black or grey
Operational temperature range at full performance	+5°C~+45°C
Suitable for patient hoist application	

Drawing

Standard Dimensions
(mm)



Load and Speed

CODE	Load (N)		Self Locking Force (N)	Typical Current (A)		Typical Speed (mm/s)	
	Push	Pull		No Load 32V DC	With Load 24V DC	No Load 32V DC	With Load 24V DC
Motor Speed (4300RPM, Long motor)							
B	6000	6000	6000	2	7.1	14.7	8.9
C	8000	6000	8000	1.8	8.6	13.2	7.6
D	10000	6000	10000	1.5	8.6	9.8	5.7
Motor Speed (3800RPM, Long motor)							
F	6000	6000	6000	1.8	6.4	13.4	7.8
G	8000	6000	8000	1.6	7.8	12.0	6.5
H	10000	6000	10000	1.3	7.8	9.0	4.8

Note

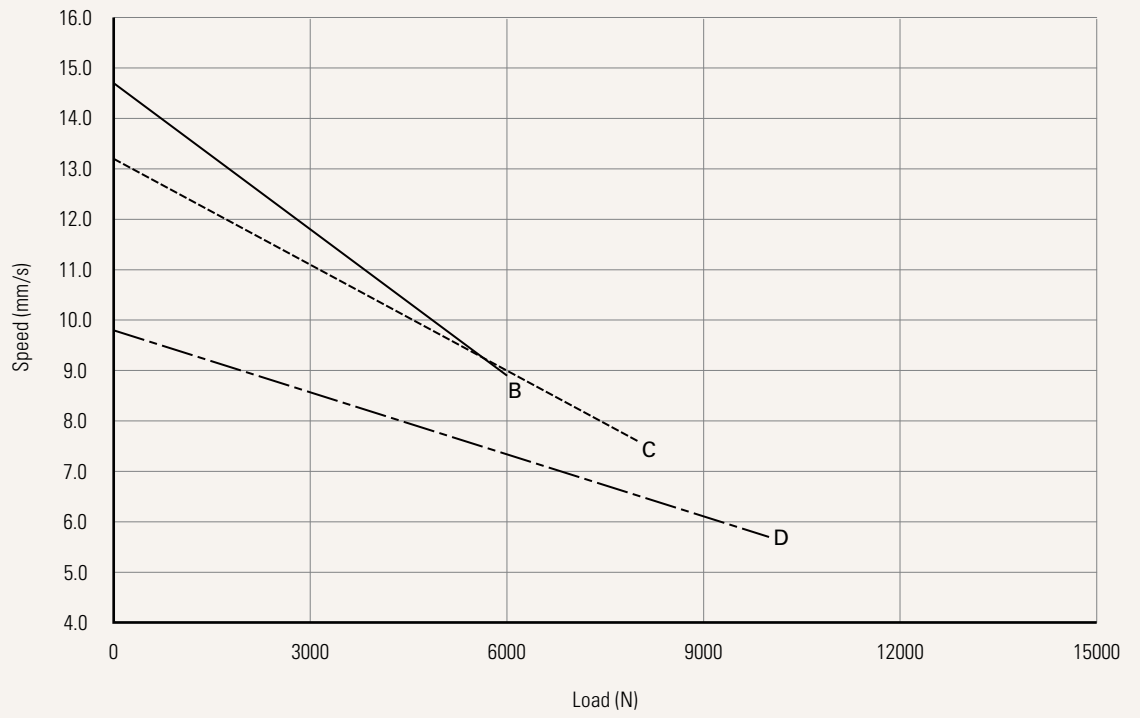
- Please refer to the approved drawing for the final authentic value.
- This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.
- The current & speed in table are tested with 24V DC motor. With a 12V DC motor, the current is approximately twice the current measured in 24V DC. With a 36V DC motor, the current is approximately two-thirds the current measured in 24V DC. Speed will be similar for all the voltages.
- The current & speed in table are tested when the actuator is extending under push load.
- The current & speed in table and diagram are tested with TiMOTION control boxes, and there will be around 10% tolerance depending on different models of the control box. (Under no load condition, the voltage is around 32V DC. At rated load, the voltage output will be around 24V DC)
- Standard stroke: Min. ≥ 25 mm, Max. please refer to below table.

CODE	Load (N)	Max Stroke (mm)
B / F	6000	350
C / G	8000	300
D / H	10000	450

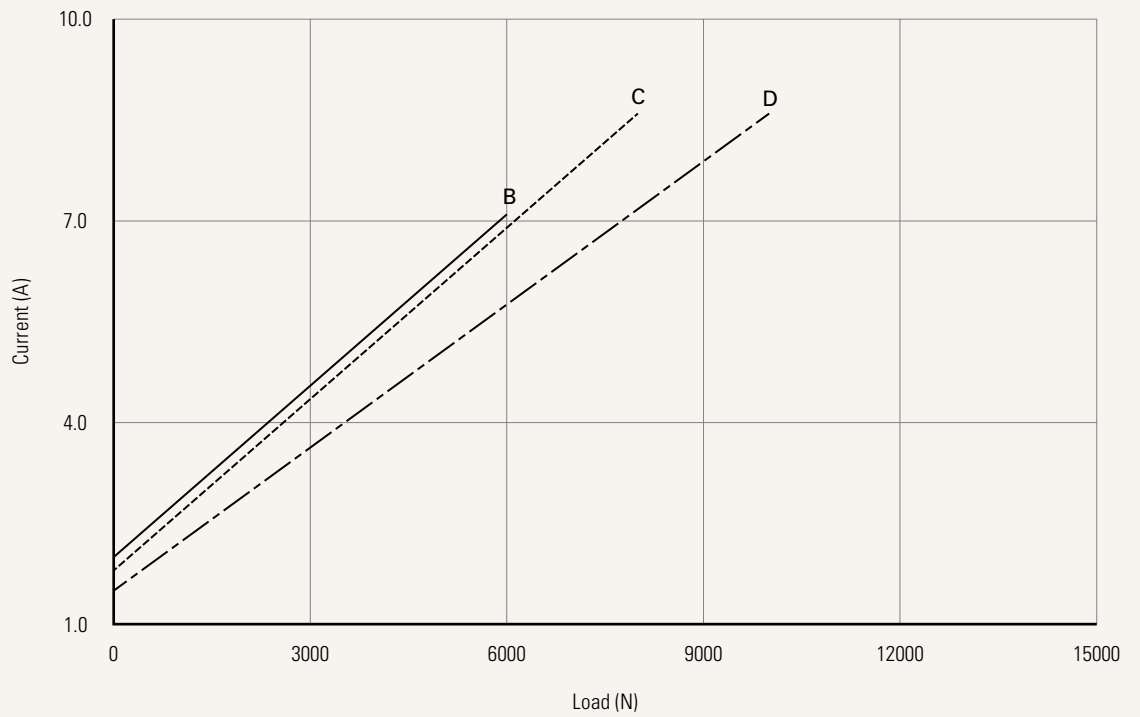
Performance Data (24V DC Motor)

Motor Speed (4300RPM, Long motor)

Speed vs. Load



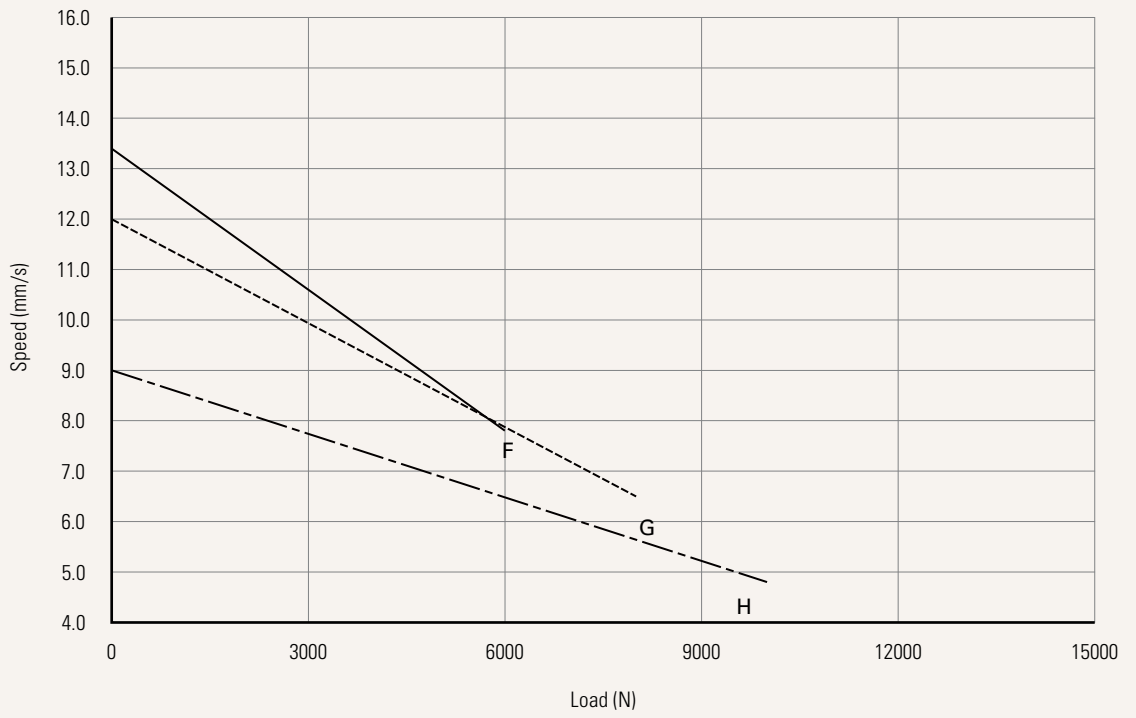
Current vs. Load



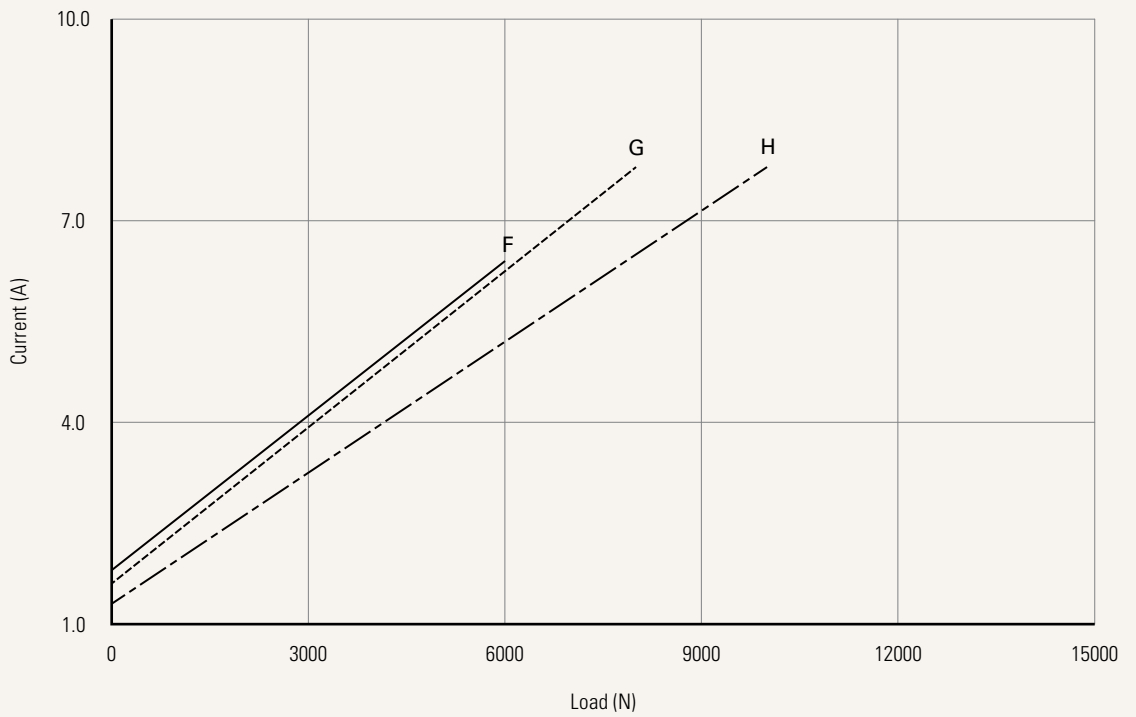
Performance Data (24V DC Motor)

Motor Speed (3800RPM, Long motor)

Speed vs. Load



Current vs. Load



Voltage	2 = 24V DC	5 = 24V DC, PTC		
Load and Speed	See page 2			
Stroke (mm)	See page 2			
Retracted Length (mm)	See page 7			
Rear Attachment (mm)	7 = Aluminum casting, clevis U, slot 8.2, depth 17.0, hole 12.2 C = Aluminum casting, clevis U, slot 8.2, depth 17.0, hole 10.2, with plastic T-bushing			
See page 8				
Front Attachment (mm)	1 = Inner tube with punched hole + plastic cap, no slot, hole 10.2, with plastic bushing	9 = Aluminum casting, clevis U, slot 6.2, depth 17.0, hole 10.2, with plastic T-bushing		
See page 8-9	2 = Inner tube with punched hole + plastic cap, no slot, hole 12.2	J = Aluminum casting, no slot, hole 10.2, for dental chair		
	5 = Inner tube with punched hole, no slot, hole 10.2, with plastic bushing	N = Iron CNC, clevis U, slot 6.2, depth 17.0, hole 10.0		
	6 = Inner tube with punched hole, no slot, hole 12.2	O = Iron CNC, clevis U, slot 6.2, depth 17.0, hole 12.0		
	7 = Aluminum casting, clevis U, slot 6.2, depth 17.0, hole 10.2	P = Iron CNC, clevis U, slot 8.2, depth 17.0, hole 10.0		
	8 = Aluminum casting, clevis U, slot 6.2, depth 17.0, hole 12.2	Q = Iron CNC, clevis U, slot 8.2, depth 17.0, hole 12.0		
Direction of Rear Attachment (Counterclockwise)	1 = 0°	3 = 90°		
See page 9				
Color	1 = Black	2 = Pantone 428C		
IP Rating	1 = Without	2 = IP54	3 = IP66	5 = IP66W
Special Function for Spindle Sub-assembly	0 = Without	3 = Standard push only + safety nut		
	1 = Safety nut	4 = Electrical anti-pinch		
	2 = Standard push only	5 = Electrical anti-pinch + safety nut		
Function for Limit Switches	1 = Two switches at full retracted / extended positions to cut current			
See page 9				
Output Signal	0 = Without	2 = Hall sensor * 2		
	1 = Hall sensor * 1	3 = POT		
Connector	0 = Without, for socket on gear box (Molex 8P)	F = DIN 6P, 180° plug		
See page 10	1 = DIN 6P, 90° plug	Q = Molex 6P, 90° plug, without anti-clip		
	2 = Tinned leads	R = Molex 6P, 180° plug		
Cable Length (mm)	0 = Without, for socket on gear box (Molex 8P)	6 = Straight, 2000		
	1 = Straight, 500	7 = Curly, 200		
	3 = Straight, 1000	8 = Curly, 400		
	5 = Straight, 1500			
Brake	0 = Without	9 = Spindle brake (4.5N) + Motor brake		
	8 = Double Spindle brake (4.5N*2)	M = Motor brake		

Voltage	2 = 24V DC	5 = 24V DC, PTC		
Load and Speed	See page 2			
Stroke (mm)	See page 2			
Retracted Length (mm)	See page 7			
Rear Attachment (mm)	C = Aluminum casting, clevis U, slot 8.2, depth 17.0, hole 10.2, T bushing			
	See page 8			
Front Attachment (mm)	F = Aluminum casting, clevis U, slot 8.2, depth 19.0, hole 10.2, T bushing, for Manual Release			
	I = Aluminum casting, U clevis, slot 8.2, depth 39.0, hole 10.2, with plastic T-bushing, for manual release			
	G = Aluminum casting, U clevis, slot 8.2, depth 19.0, hole 10.2, with plastic T-bushing, Without press down for manual release			
Direction of Rear Attachment (Counterclockwise)	1 = 0°	3 = 90°		
	See page 9			
Color	2 = Pantone 428C			
IP Rating	2 = IP54	3 = IP66	5 = IP66W	
Special Function for Spindle Sub-assembly	6 = Mechanical push only + safety nut			
	7 = Mechanical push only + Electrical anti-pinch + safety nut			
Function for Limit Switches	1 = Two switches at full retracted / extended positions to cut current			
	See page 9			
Output Signal	0 = Without	1 = Hall sensor * 1	2 = Hall sensor * 2	
Connector	Q = Molex 6P, 90° plug	R = Molex 6P, 180° plug		
	See page 10			
Cable Length (mm)	1 = Straight, 500	3 = Straight, 1000	5 = Straight, 1500	6 = Straight, 2000
Brake	8 = Double Spindle brake (4.5N * 2)			
Load Type	T = Push			

Retracted Length (mm)

1. Calculate $A+B = Y$
2. Retracted length needs to $\geq \text{Stroke}+Y$

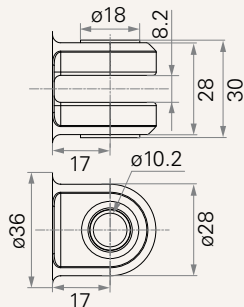
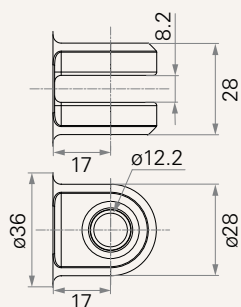
A.	
Front Attach.	General
1, 2, 5, 6	+190
7, 8, 9	+202
J	+193

B. Load & Stroke			
Stroke (mm)	Load (N) General		
	= 6000	= 8000	= 10000
25~150	-	-	+5
151~200	-	+5	+10
201~250	+5	+10	+15
251~300	+10	+15	+20
301~350	+15	+20	+25
351~400	+20	+25	+30
401~450	+25	+30	+35
451~500	+30	+35	+40
501~550	+35	+40	+45
551~600	+40	+45	+50
601~650	+45	+50	+55
651~700	+50	+55	x
701~750	+55	+60	x
751~800	+60	+65	x
801~850	+65	x	x
851~900	+70	x	x

Rear Attachment (mm)

7 = Aluminum casting, clevis U, slot 8.2, depth 17.0, hole 12.2

C = Aluminum casting, clevis U, slot 8.2, depth 17.0, hole 10.2, with plastic T-bushing



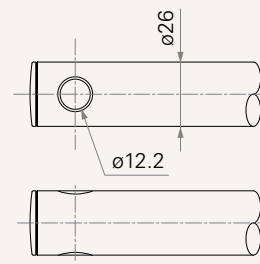
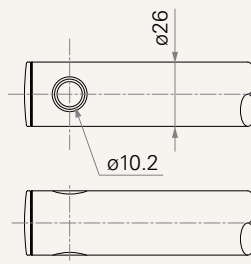
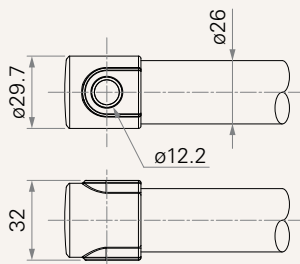
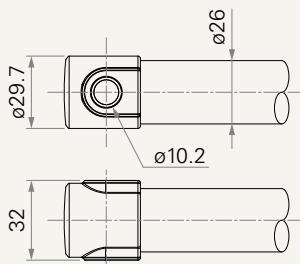
Front Attachment (mm)

1 = Inner tube with punched hole + plastic cap, no slot, hole 10.2, with plastic bushing

2 = Inner tube with punched hole + plastic cap, no slot, hole 12.2

5 = Inner tube with punched hole, no slot, hole 10.2, with plastic bushing

6 = Inner tube with punched hole, no slot, hole 12.2

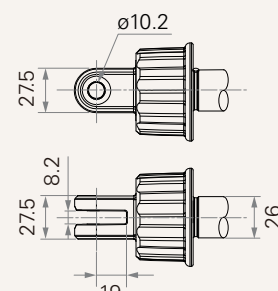
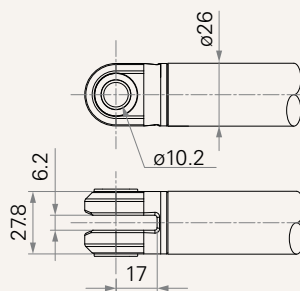
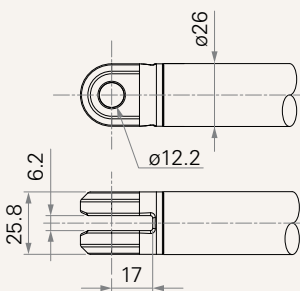
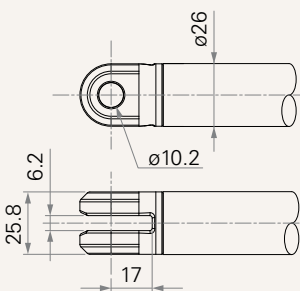


7 = Aluminum casting, clevis U, slot 6.2, depth 17.0, hole 10.2

8 = Aluminum casting, clevis U, slot 6.2, depth 17.0, hole 12.2

9 = Aluminum casting, clevis U, slot 6.2, depth 17.0, hole 10.2, with plastic T-bushing

F = Aluminum casting, clevis U, slot 8.2, depth 19.0, hole 10.2, T bushing, for Manual Release

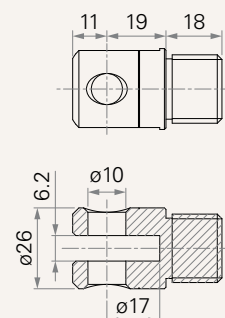
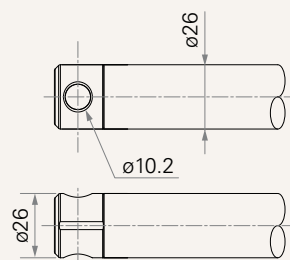
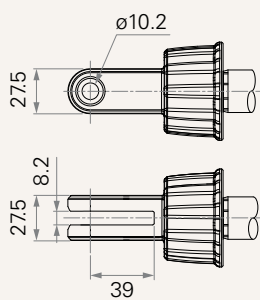
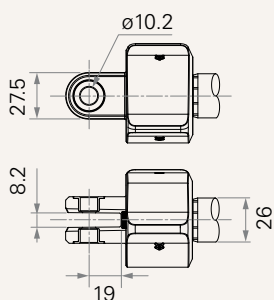


G = Aluminum casting, U clevis, slot 8.2, depth 19.0, hole 10.2, with plastic T-bushing, Without press down for manual release

I = Aluminum casting, U clevis, slot 8.2, depth 39.0, hole 10.2, with plastic T-bushing, for manual release

J = Aluminum casting, no slot, hole 10.2, for dental chair

N = Iron CNC, clevis U, slot 6.2, depth 17.0, hole 10.0

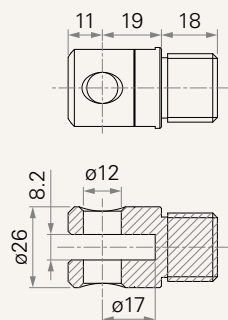
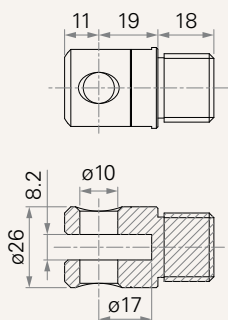
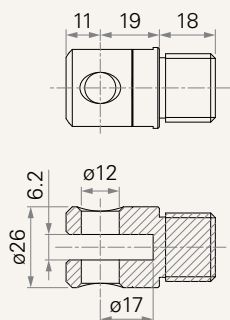


Rear Attachment (mm)

O = Iron CNC, clevis U, slot 6.2, depth 17.0, hole 12.0

P = Iron CNC, clevis U, slot 8.2, depth 17.0, hole 10.0

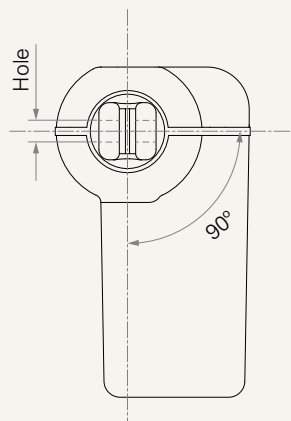
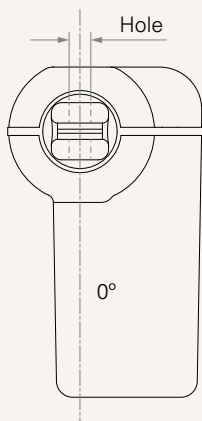
Q = Iron CNC, clevis U, slot 8.2, depth 17.0, hole 12.0



Direction of Rear Attachment (Counterclockwise)

1 = 0°

3 = 90°



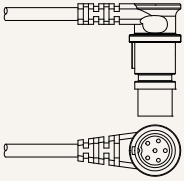
Functions for Limit Switches

Wire Definitions

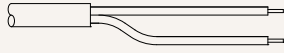
CODE	Pin					
	1 (Green)	2 (Red)	3 (White)	4 (Black)	5 (Yellow)	6 (Blue)
1	extend (VDC+)	N/A	N/A	N/A	retract (VDC+)	N/A

Connector

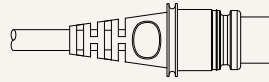
1 = DIN 6P, 90° plug



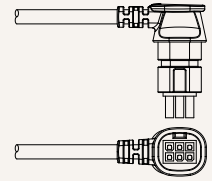
2 = Tinned leads



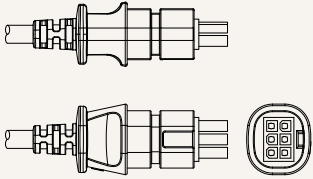
F = DIN 6P, 180° plug



Q = Molex 6P, 90° plug, without anti-clip



R = Molex 6P, 180° plug



Terms of Use

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