

# TA16

series



## Product Segments

- **Care Motion**
- **Comfort Motion**
- **Ergo Motion**
- **Industrial Motion**

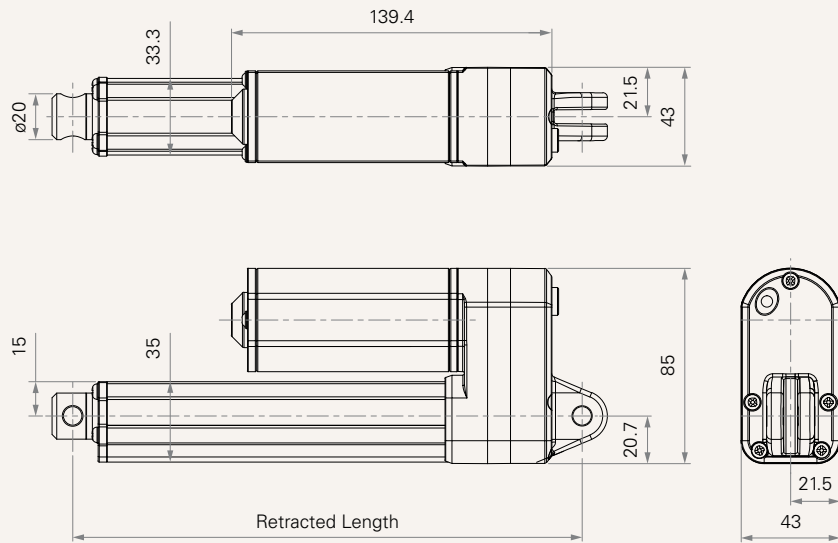
TiMOTION's TA16 series linear actuator is similar to the TA2 linear actuator, but is specifically designed for low-noise applications where a compact linear actuator is needed. It is available with optional IP66 protection and Hall sensors for position feedback. Certificates for the TA16 include IEC60601-1, ES60601-1, IEC60601-1-2, UL962, and EMC.

### General Features

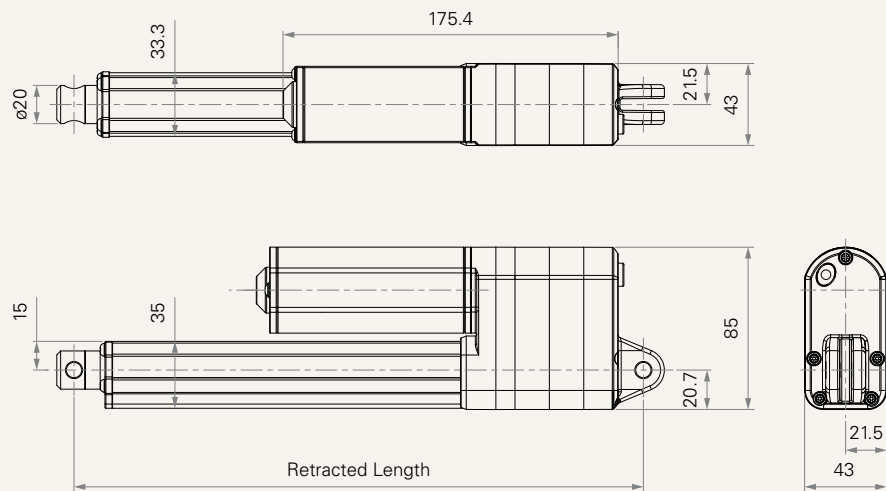
Max. load	3,500N (push / pull)
Max. speed at max. load	6.2mm/s
Max. speed at no load	58.2mm/s
Retracted length	≥ Stroke + 112mm
IP rating	IP66
Certificate	IEC60601-1, ES60601-1, IEC60601-1-2, UL962, EMC
Stroke	20~600mm
Output Signals	POT, Hall sensor(s)
Voltage	12 / 24 / 36 / 48V DC; 12 / 24V DC (PTC)
Color	Silver
Operational temperature range at full performance	+5°C~+45°C
With very low noise, small size for easy installation	
Suitable for patient hoist application	

**Drawing**

Dimensions  
without Output Signal  
or with Hall Sensors  
(mm)



Dimensions with POT  
(mm)



### Load and Speed

CODE	Load (N)		Self Locking Force (N)	Typical Current (A)		Typical Speed (mm/s)	
	Push	Pull		No Load 32V DC	With Load 24V DC	No Load 32V DC	With Load 24V DC
<b>Motor Speed (3800RPM, Duty Cycle 10%)</b>							
<b>A</b>	2500	2500	2500	1.7	2.6	5.2	3.0
<b>B</b>	2000	2000	2000	1.7	2.6	8.3	4.7
<b>C</b>	1500	1500	1500	1.7	2.6	11.9	7.0
<b>D</b>	1000	1000	1000	1.7	2.6	17.7	10.3
<b>E</b>	500	500	500	1.7	3.5	58.2	28.8
<b>Motor Speed (5200RPM, Duty Cycle 10%)</b>							
<b>G</b>	3500	3500	3500	2.0	4.7	11.0	6.2
<b>J</b>	2000	2000	2000	2.0	3.7	17.0	10.5
<b>K</b>	1500	1500	1500	2.0	3.5	23.5	13.5

### Note

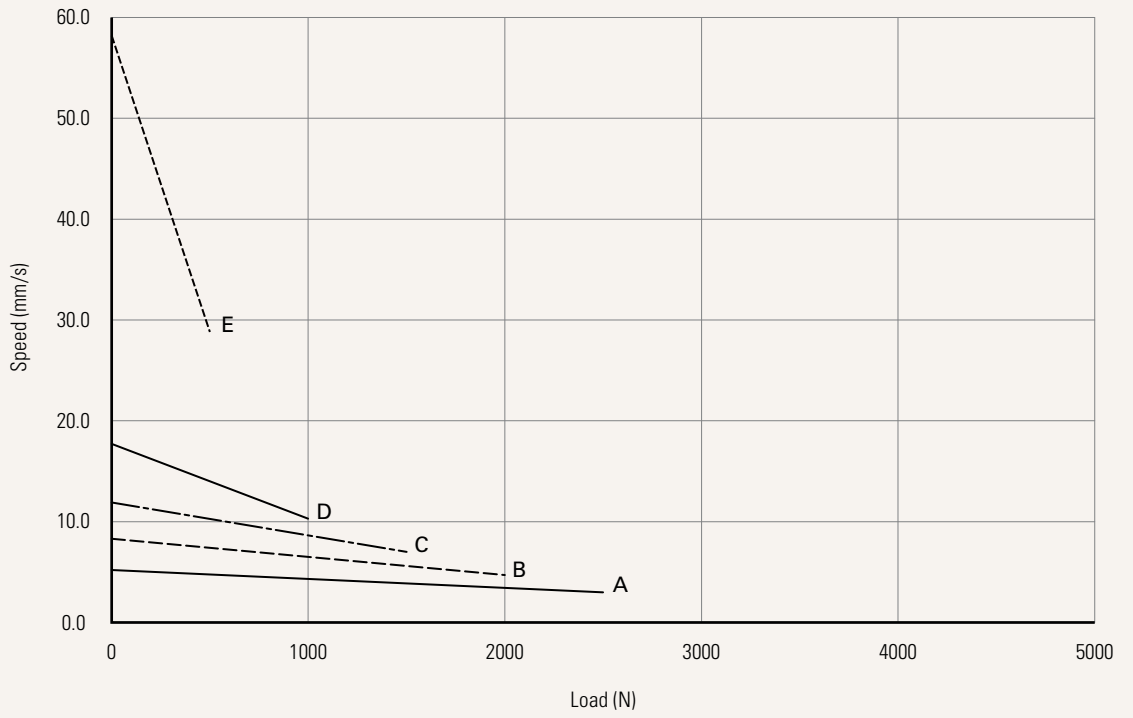
- 1 Please refer to the approved drawing for the final authentic value.
- 2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.
- 3 The current & speed in table are tested with 24V DC motor. With a 12V DC motor, the current is approximately twice the current measured in 24V DC. With a 36V DC motor, the current is approximately two-thirds the current measured in 24V DC. With a 48V DC motor, the current is approximately half the current measured in 24V DC. Speed will be similar for all the voltages.
- 4 The current & speed in table and diagram are tested with TiMOTION control boxes, and there will be around 10% tolerance depending on different models of the control box. (Under no load condition, the voltage is around 32V DC. At rated load, the voltage output will be around 24V DC)
- 5 Standard stroke: Please refer to below table.

CODE	Load (N)	Min Stroke (mm)	Max Stroke (mm)
<b>E</b>	≤ 500	38	600
<b>D</b>	≤ 1000	20	600
<b>C, K</b>	≤ 1500	20	500
<b>B, J</b>	≤ 2000	20	450
<b>A</b>	≤ 2500	20	400
<b>G</b>	≤ 3500	20	300

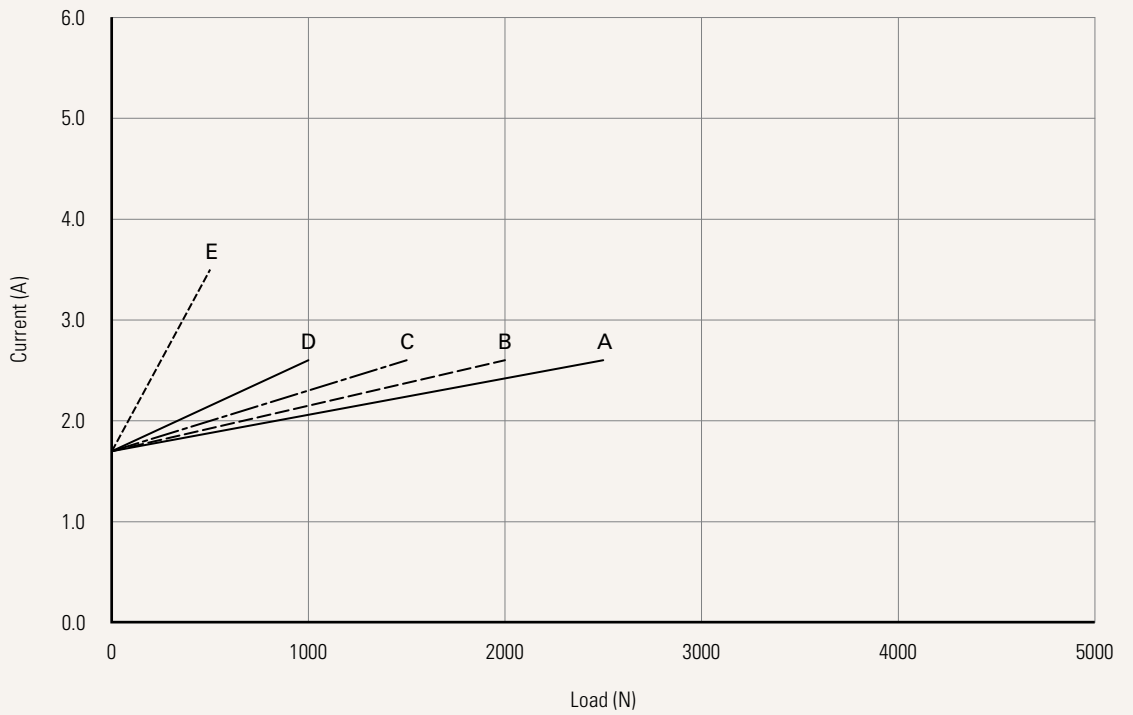
**Performance Data (24V DC Motor)**

Motor Speed (3800RPM, Duty Cycle 10%)

Speed vs. Load



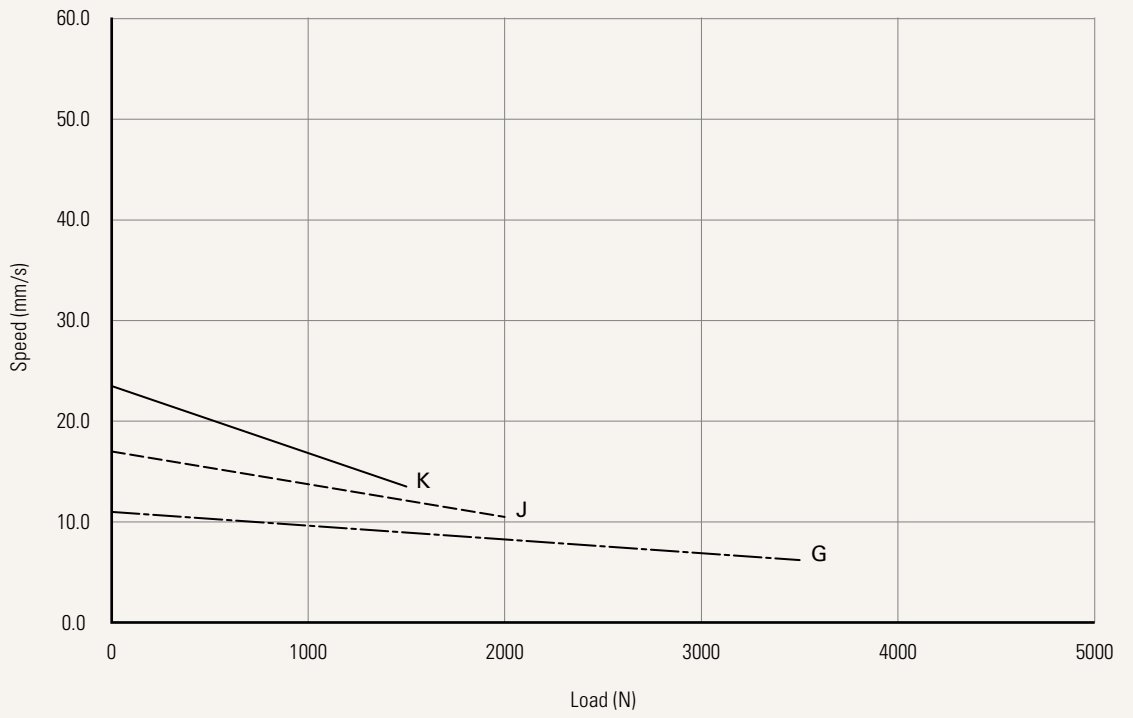
Current vs. Load



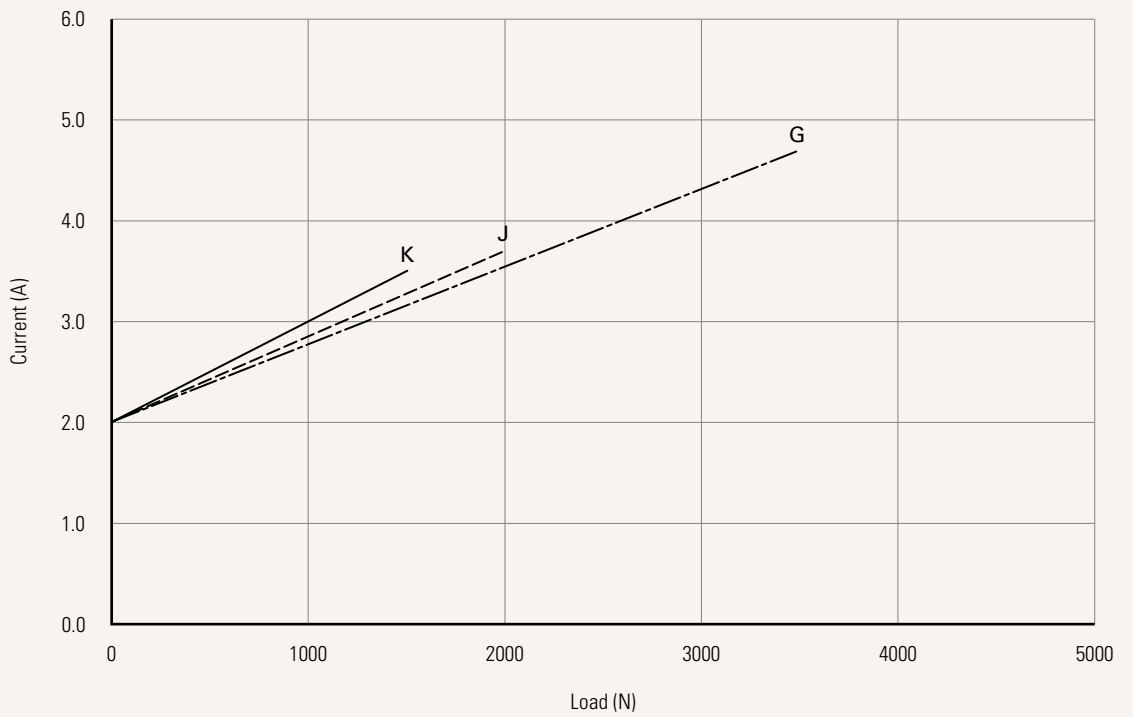
**Performance Data (24V DC Motor)**

Motor Speed (5200RPM, Duty Cycle 10%)

Speed vs. Load



Current vs. Load



<b>Voltage</b>	1 = 12V DC 2 = 24V DC	3 = 36V DC 4 = 48V DC	5 = 24V DC, PTC 6 = 12V DC, PTC
<b>Load and Speed</b>	<a href="#">See page 3</a>		
<b>Stroke (mm)</b>	<a href="#">See page 3</a>		
<b>Retracted Length (mm)</b>	<a href="#">See page 7</a>		
<b>Rear Attachment (mm)</b> <a href="#">See page 8</a>	1 = Aluminum casting, U clevis, width 6.0, depth 12.2, hole 6.4, one piece casting with gear box 2 = Aluminum casting, U clevis, width 6.0, depth 12.2, hole 8.0, one piece casting with gear box 3 = Aluminum casting, U clevis, width 6.0, depth 12.2, hole 10.0, one piece casting with gear box		
<b>Front Attachment (mm)</b> <a href="#">See page 8</a>	1 = Aluminum casting, no slot, hole 6.4 2 = Aluminum casting, no slot, hole 8.0 3 = Aluminum casting, no slot, hole 10.0 4 = Aluminum casting, U clevis, width 6.0, depth 13.0, hole 6.4		5 = Aluminum casting, U clevis, width 6.0, depth 13.0, hole 8.0 6 = Aluminum casting, U clevis, width 6.0, depth 13.0, hole 10.0
<b>Direction of Rear Attachment (Counterclockwise)</b> <a href="#">See page 8</a>	1 = 90°	2 = 0°	
<b>IP Rating</b>	1 = Without	2 = IP54	3 = IP66
<b>Functions for Limit Switches</b> <a href="#">See page 9</a>	1 = Two switches at full retracted / extended positions to cut current 2 = Two switches at full retracted / extended positions to cut current + 3rd LS to send signal 3 = Two switches at full retracted / extended positions to send signal 4 = Two switches at full retracted / extended positions to send signal + 3rd LS to send signal		
<b>Special Functions for Spindle Sub-Assembly</b>	0 = Without (Standard) 1 = Safety nut		2 = Standard push only 3 = Standard push only + safety nut
<b>Output Signals</b>	0 = Without	1 = POT	4 = Hall sensor * 1 5 = Hall sensor * 2
<b>Connector</b> <a href="#">See page 9</a>	1 = DIN 6P, 90° plug 2 = Tinned leads 4 = Big 01P, plug	C = Y cable (For direct cut system, water proof, anti pull) E = Molex 8P, plug F = DIN 6P, 180° plug	G = Audio plug
<b>Cable Length (mm)</b>	0 = Straight, 100 1 = Straight, 500 2 = Straight, 750	3 = Straight, 1000 4 = Straight, 1250 5 = Straight, 1500	6 = Straight, 2000 7 = Curly, 200 8 = Curly, 400 B-H = For direct cut system <a href="#">See page 9</a>

## Retracted Length (mm)

1. Calculate  $A+B+C+D = Y$
2. Retracted length needs to  $\geq$  Stroke + Y

### A. Rear / Front Attach.

Front Attach.	Rear Attach.
	1, 2, 3
<b>1, 2, 3</b>	+112
<b>4, 5, 6</b>	+122

### B. Load V.S. Stroke

Stroke (mm)	Load & Speed Type	
	A, B, C, D, E, J, K	G
<b>20~150</b>	-	+13
<b>151~200</b>	+8	+21
<b>201~250</b>	+8	+21
<b>251~300</b>	+13	+26
<b>301~350</b>	+13	+26
<b>351~400</b>	+18	+31
<b>401~450</b>	+23	+36
<b>451~500</b>	+28	+41
<b>501~550</b>	+33	+46
<b>551~600</b>	+38	+51

### C. Load V.S. Spindle Functions

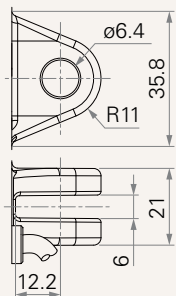
Spindle Functions	Load & Speed Type	
	A, B, C, D, E, J, K	G
<b>0</b>	-	-
<b>1</b>	+10	+5
<b>2</b>	+2	+2
<b>3</b>	+12	+7

### D. Output Signals

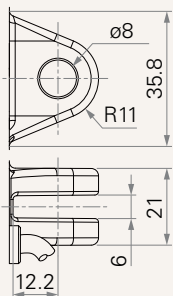
CODE	
<b>0, 4, 5</b>	-
<b>1</b>	+36

## Rear Attachment (mm)

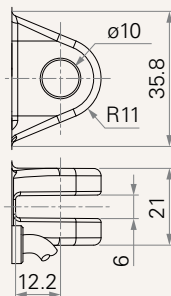
1 = Aluminum casting, U clevis, width 6.0, depth 12.2, hole 6.4, one piece casting with gear box



2 = Aluminum casting, U clevis, width 6.0, depth 12.2, hole 8.0, one piece casting with gear box

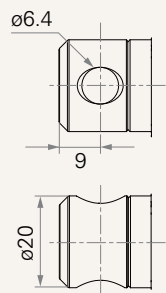


3 = Aluminum casting, U clevis, width 6.0, depth 12.2, hole 10.0, one piece casting with gear box

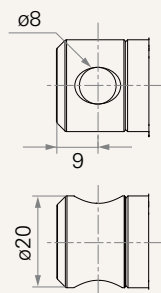


## Front Attachment (mm)

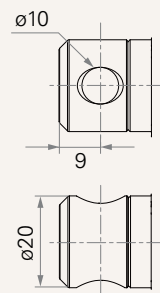
1 = Aluminum casting, no slot, hole 6.4



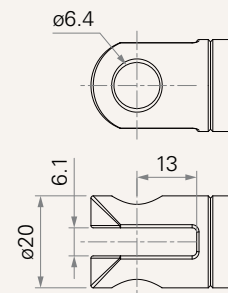
2 = Aluminum casting, no slot, hole 8.0



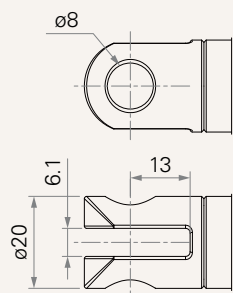
3 = Aluminum casting, no slot, hole 10.0



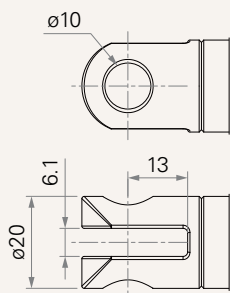
4 = Aluminum casting, U clevis, width 6.0, depth 13.0, hole 6.4



5 = Aluminum casting, U clevis, width 6.0, depth 13.0, hole 8.0

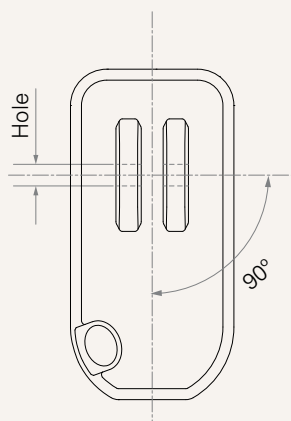


6 = Aluminum casting, U clevis, width 6.0, depth 13.0, hole 10.0

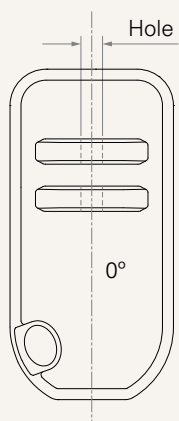


## Direction of Rear Attachment (Counterclockwise)

1 = 90°



2 = 0°





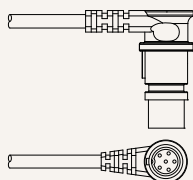
## Functions for Limit Switches

### Wire Definitions

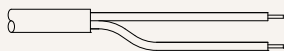
CODE	Pin					
	● 1 (Green)	● 2 (Red)	○ 3 (White)	● 4 (Black)	● 5 (Yellow)	● 6 (Blue)
1	extend (VDC+)	N/A	N/A	N/A	retract (VDC+)	N/A
2	extend (VDC+)	N/A	middle switch pin B	middle switch pin A	retract (VDC+)	N/A
3	extend (VDC+)	common	upper limit switch	N/A	retract (VDC+)	lower limit switch
4	extend (VDC+)	common	upper limit switch	medium limit switch	retract (VDC+)	lower limit switch

### Connector

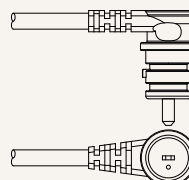
1 = DIN 6P, 90° plug



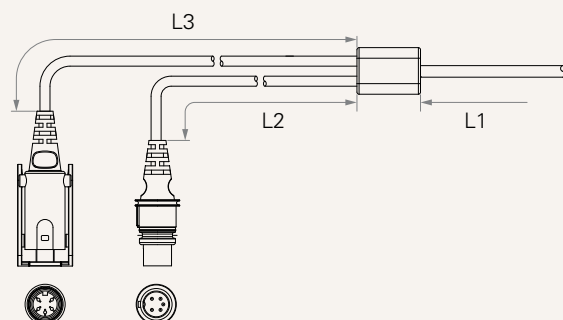
2 = Tinned leads



4 = Big 01P, plug



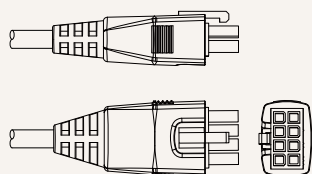
C = Y cable (For direct cut system, water proof, anti pull)



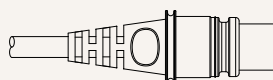
### Cable Length for Direct Cut System (mm)

CODE	L1	L2	L3
B	100	100	100
C	100	1000	400
D	100	2700	500
E	1000	100	100
F	100	600	1000
G	1500	1000	1000
H	100	100	1200

E = Molex 8P, plug



F = DIN 6P, 180° plug



G = Audio plug



### Terms of Use

The user is responsible for determining the suitability of TiMOTION products for a specific application. TiMOTION products are subject to change without prior notice.