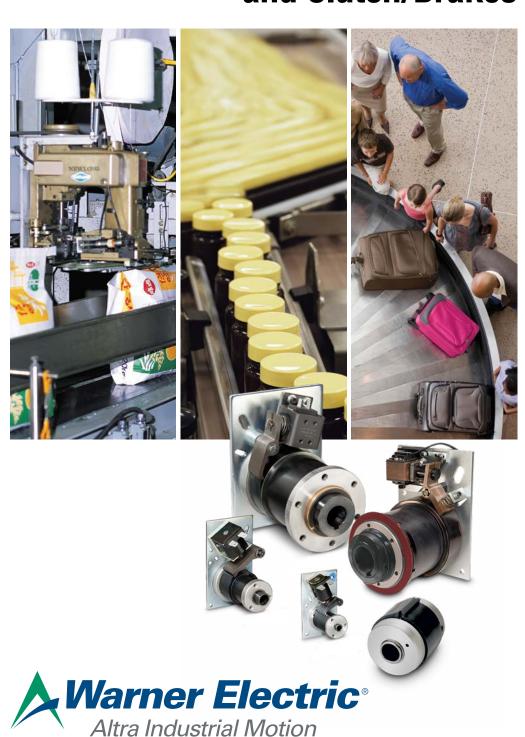
# Wrap Spring Clutches and Clutch/Brakes



# Warner Electric

Founded in 1927, Warner Electric has grown to become a global leader in the development of innovative electromagnetic clutch & brake solutions. Warner Electric engineers utilize the latest materials and manufacturing technologies to design long life, easy-to-use clutches and brakes that provide improved accuracy and repeatability. Warner Electric offers the broadest selection of industrial clutches, brakes, controls and web tension systems available from a single manufacturer.

Reliable Warner Electric components are used in a wide range of markets including material handling, packaging machinery, food & beverage, elevator & escalator, turf & garden, agriculture, off-highway, forklift, crane and motion control. Applications include conveyors, lift trucks, wrapping machines, servo motors, capping equipment, combines, balers, baggage handling systems, military vehicles, hoists and lawn mowers.

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Within the Warner Electric Interactive eCATALOG, you can start your search for basic components, such as clutches or brakes, and then quickly refine your search from hundreds of possibilities to one that meets your specific power transmission requirements for NEMA, input/output configurations and other factors. You can also download specifications and PDF pages or submit an RFQ for any of your selections.

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# Warner Electric

# WRAP SPRING CLUTCHES AND CLUTCH/BRAKES

Warner Electric offers a complete line of standard wrap spring clutches and clutch/brakes, available for immediate delivery through our nationwide network of power transmission distributors. As the industry leader in clutch/brake technology you can count on Warner Electric for complete application assistance and after sale service.



# **CB Series Clutch/Brakes**

Electrically actuated clutch/brake package. Designed for applications requiring a continuous rotational input that is converted into starting and stopping a load. Operate from either an AC or DC power source.

# **Super CB Series Clutch/Brakes**

High performance clutch/brake packages feature extraordinary long life. Ideal for demanding applications involving continuous high cycle rates under heavy load conditions.

### **WSC Series Clutches**

Basic design wrap spring clutches are mechanically actuated and require no electrical power. Available in three configurations for overrunning, start-stop and single revolution applications. Very compact. They deliver more torque than a friction clutch of the same size.



# **Wrap Spring Product Line**

Page 2

# **Principle of Operation**

Page 3

# **Application Examples**

Page 4

# **Selection**

Page 6

# **CB Mounting Requirements**

Page 8

# **CB Stop Collar Adjustment**

Page 10

# **CB Series Clutch/Brakes**

Page 11

# **SCB Series Clutch/Brakes**

Page 19

# SCB-10 Features & Improvements

Page 25

# **WSC Series Clutches**

Page 26

# **Power Supplies**

Page 32

# **CB Spring Differential Setting**

Page 34

# **CB Actuator Gap Adjustment**

Page 35

# **Application Engineering**

Page 36

# **Part Numbers**

Page 39

# **Metric Part Numbers**

Page 40

# **Application Data Form**

Page 41

# **Wrap Spring Product Line**

# **CB Series**



# **Clutch/Brake Package**

Each CB Series unit is a completely self-contained, packaged clutch/brake assembly designed to start and stop a load rapidly and accurately without any cumulative error. In fact, at speeds up to 1800 rpm, loads are started and stopped within  $\pm 1/2^{\circ}$  per revolution. CB Series units are solenoid actuated with standard models available in 12, 24, or 90 VDC as well as 115 VAC configurations.

### **Accurate**

Start and stop positioning can be maintained within  $\pm 1/2^{\circ}$  at speeds up to 1800 rpm. The stop point is adjustable by using the adjustable control collar.

# **Self-Contained**

Each CB Series unit is completely self-contained. Assembly and testing before shipment ensure reliable and trouble-free operation.

# Interchangeability

The CB Series is completely interchangeable with other comparable clutch/brake packages.

### **Features**

- □ CW or CCW rotation
- ☐ Anti-back: anti-overrun feature
- ☐ 12, 24 or 90 VDC, 115 VAC operation
- 1, 2 or 4 stop collars standard; special stop collars also available (up to 24 stops)
- ☐ Adjustable stop collar
- ☐ Six standard sizes
- ☐ Torque ratings from 25 lb.in. to 5000 lb.in.

# **SCB Series**



# Long Life Clutch/Brake

The Super CB Series is a high performance version of the standard CB Series, providing up to five times the life. The SCB Series is recommended for heavy-duty applications requiring maximum torque, high cycle rates and minimum maintenance. Like the CB Series, each Super CB Series unit is a complete, factory-assembled package, ready for installation.

### **Features**

- ☐ Heavy duty design
- ☐ High cycle rate performance
- ☐ Long life up to five times that of a standard CB model
- ☐ Three standard models
- ☐ Torque ratings up to 5000 lb.in.
- □ CW or CCW rotation
- ☐ Anti-back: anti-overrun feature
- ☐ 12, 24, 90 VDC or 115 VAC operation
- 1, 2 or 4 stop collars standard; special stop collars also available (up to 24 stops)
- ☐ Adjustable stop collars

# **WSC Series**



# **Wrap Spring Clutches**

WSC Series clutches are simple, mechanically actuated devices providing high torque in a compact design. Specific models are available for use as an overrunning/one-way clutch (Model O), as a start/coast-to-stop clutch (Model SS), or as a single revolution clutch (Model S).

### Overrunning/One-Way (Model 0)

This clutch continually drives the load. The load is allowed to overrun the input, should its speed exceed input speed. In the reverse direction the unit acts as a one-way clutch, preventing the load from backing up.

### Start/Coast-To-Stop (Model SS)

The start/stop clutch is engaged until the collar that contains the spring tang is disengaged. Once it is stopped, the load is disengaged and coasts to a stop.

# Start/Stop - Single Revolution (Model S)

Attaching one end of the spring to the output hub results in a single revolution clutch. The load is stopped through the spring to the collar. Precise non-cumulative error single revolution cycling is achieved. Braking torque equals 10% of the maximum torque rating.

### **Features**

- ☐ Five standard sizes
- ☐ Torque ratings from 25 lb.in. to 2500 lb.in.
- ☐ Hub or shaft input
- Multiple stop collarsOver-travel stop
- ☐ Anti-overrun
- ☐ Adjustable stop feature

# **Basic Design Principles**

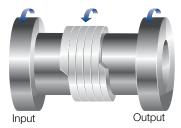
# **Principle of Operation**

The three basic components of the wrap spring clutch are the input hub, output hub, and spring. The inside diameter of the spring is slightly smaller than the outside diameter of the two hubs. Rotation at the input hub in the direction of the arrow engages the spring and positively locks the two hubs together. Adding a control tang enables the spring to be disengaged, allowing the input hub to overrun.

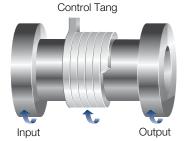
# **Combination Clutch/Brake**

The control tangs are used to hold open the clutch or brake spring, which are wrapped in opposite directions. When the clutch and brake control tangs rotate with the input hub, the input hub and output shaft are engaged by the clutch spring. When the stop collar locks the control tang of the brake spring, it wraps down engaging the output shaft to the brake hub. The clutch spring unwraps at the same time, allowing the input hub to freely rotate.

# **Design Configurations**

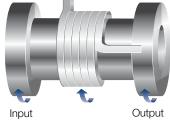


Model 0

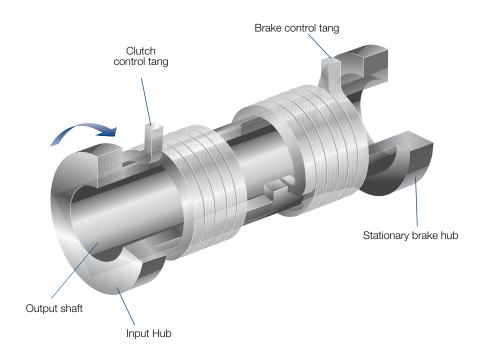


Model SS

Control Tang



**Model S** 



# **Overrunning (One Way Clutch)**

When the input hub is rotated in the direction shown, the spring wraps down and engages the input to the output hub. When the input hub is stopped or reversed, the spring unwraps, allowing the output hub to overrun. These clutches can also be used for backstopping and indexing. In the backstopping mode, either the input or output hub is attached to a fixed member and the other hub on a rotating part. Rotation is permitted in one direction, but locked in reverse rotation. Indexing provides an accurate and smooth intermittent rotary output from reciprocating input in variable angular increments.



# Start/Coast-To-Stop Clutch (Random Positioning)

In this mode, the control tang rotates with the input hub, thus the clutch is engaged. When the stop collar locks the control tang, the spring unwraps, allowing the output hub to coast while the input hub continues to run.



# Start/Stop – Single Revolution Clutch

In this mode another control tang is added to the spring and fixed to the output hub. When the stop collar engages the control tang, the output hub will not overrun. Remember only a maximum of 10% of the load will be stopped with the single revolution clutch.

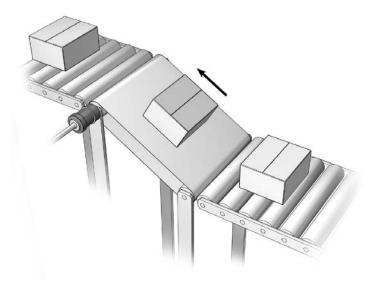


# **Application Examples**

The features of wrap spring clutches and brakes; accuracy, repeatability, high torque-to-size ratio, low power consumption and long life make them an ideal solution for a wide range of motion control applications. Basic functions include overrunning, single revolution, random positioning start-stop, high cycle rate rapid start-stops and accurate, repeatable positioning.

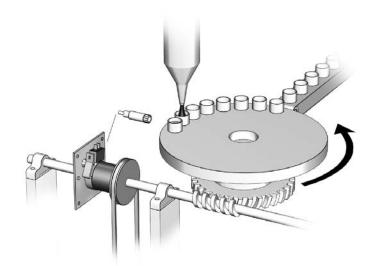
# **Typical Applications**

- □ Conveyors
- ☐ Rotary indexing tables
- $\square$  Packaging equipment
- □ Bagging machinery
- □ Collators
- ☐ Cut-off machines
- Vending machines
- □ Copiers
- ☐ Food processing equipment
- □ Paper feeds
- □ Folders
- ☐ Material handling equipment
- ☐ Riveters, staplers and stitching machines
- □ Sorters
- ☐ Punch presses
- □ Textile machines
- ☐ Film and wire processing



# **Incline Conveyor**

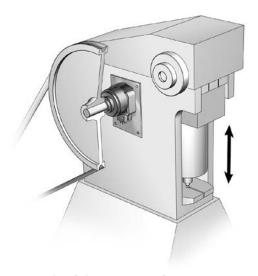
The WSC Model O mechanical wrap spring clutch provides maintenance free anti-backup protection for this incline conveyor. While the conveyor is running, the wrap spring is in overrunning mode, allowing the clutch's output to freewheel. When the conveyor drive power is removed, either intentionally or unintentionally, the spring holds the hub stationary and will prevent the conveyor and its load from back-driving.



# **Indexing Rotary Table**

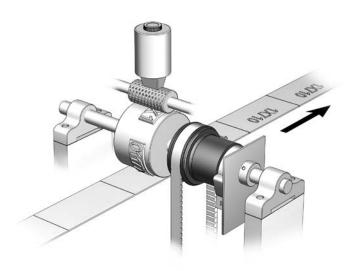
Each time the power supply provides a pulse to the solenoid of the Standard CB wrap spring clutch/brake, the table indexes one position for filling, labeling, sorting, staging or inspecting products. **CB, Super CB or WSC Model S** (with customer supplied actuator) units may each be used to perform the indexing function. Please note that while the graphic shows open gearing, a standard enclosed gearbox will work just as effectively.

# **Application Examples**



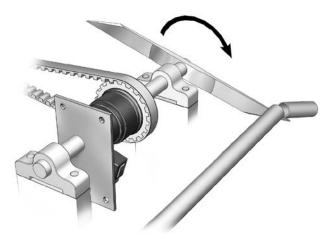
# **Industrial Stitchers and Staplers**

The motor drives a large flywheel and a cam connected to the stitcher head. The **CB** or **Super CB** wrap spring clutch/brake provides one complete cycle, always stopping at the same precise position in time for the next cycle. Warner Electric's CB and Super CB units never require any adjustment or lubrication, and provide non-cumulative error for cycle-to-cycle accuracy and consistency.



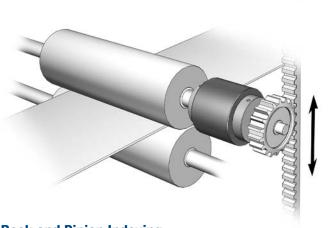
# **Print Head**

In this printing application, a photoelectric sensor detects the registration mark on the web and signals the **CB** or **Super CB** clutch/brake to cycle. Each cycle drives the print wheel in registration with the continuously moving web material. Warner Electric wrap spring clutch/brakes provide start and stop positioning within a  $\pm$  1/2° per revolution (non-cumulative), making them an excellent solution for applications requiring highly accurate, consistent performance.



### **Cut-Off Knife**

As tubing material is fed, a sensor determines when the appropriate length has been reached, and signals the clutch/brake to cycle, driving the knife to cut the tubing to the correct length. This application shows a standard option two-stop collar, which indexes 180° per sensor input, making two cuts per one complete 360° revolution. The CB or Super CB clutch/brake provides error free indexing, making the reaction time for the knife consistent from cycleto-cycle.



# **Rack and Pinion Indexing**

The unidirectional **WSC Model O** operates as an indexing drive for this application. As the rack moves upward, the wrap spring drives, providing torque to the in-feed rolls. When the rack moves downward, the wrap spring clutch freewheels, transmitting no torque to the rolls. Since the cam, pinion gear and rolls are all constant diameters, coupled with the accuracy of the WSC, the amount fed each cycle remains constant and consistent.

# For Product Selection Follow 3 Easy Steps

Wrap spring clutches and brakes are pre-packaged, pre-assembled units which are as easy to select as they are to install. The simple three step selection process includes:

**Step 1** Determine the clutch or brake function

**Step 2** Determine size function (as on page 7)

Step 3 Verify design considerations

This selection process is based on the assumption that the diameter of the shaft at the clutch or clutch/brake location has been designed through good machine design practice. For most applications, this process will determine the correct size product. When the performance requirements of a given application are marginally within the capabilities of a specific product, consider using the next larger size. In instances where

required load/speed performance data is known and unit size is uncertain, use the technical selection process starting on page 36 which will help you review the necessary aspects of your application.

# Step 1

### Determine clutch or brake function

Wrap spring clutches and brakes can perform three control functions— overrunning, start/coast-to-stop, and single revolution. Determine the function which will provide the best control for your application. Using the chart below, select the series which best fits your application requirements.

# Step 2

### **Determine size**

To select the correct size unit, determine the maximum rpm at which the clutch or brake will be operated and the shaft diameter on which the wrap spring unit will be mounted. A wrap spring clutch engages almost instantly, and, since spring wrap increases with load, the unit must be sized carefully to insure that it is correct for the application. If there is any uncertainty regarding the correct unit size, we recommend using the technical selection process starting on page 36. To select the correct wrap spring unit, locate the corresponding speed and shaft diameter points on the appropriate chart on page 7. For applications requiring speed or diameter values higher than those illustrated, please contact your local Warner Electric Distributor, your Area Sales Manager, or Warner Electric Technical Support at (800) 825-9050.

# **Selection by Function**

				Max. Torque		
Function	Performance	Wrap Spring Product	Starting lb. in. (N-m)	Stopping lb. in. (N-m)	Max. rpm	Actuation Method
Overrunning	An overrunning clutch will transmit torque in one direction only when the input hub is stopped or reversed. Consequently, the load is disengaged and free to rotate or overrun.	WSC Series Model O	2,500 (282.5)	N/A	1,800	Reverse input rotation
Engaged in one direction only						
Start/Coast-To-Stop	A start/coast-to-stop clutch will engage and disengage a load either by mechanical or electrical actuation. Start/coast-to-stop clutches provide a random stop position for the load.	WSC Series Model SS	2,500 (282.5)	0	1,800	Mechanical
Random Positioning						
Single Revolution	A single revolution clutch or clutch/brake will accurately position a load with no	WSC Series Model S	2,500 (282.5)	250 (282.5)	1,800	Mechanical
	cumulative error for each single revolution cycle. Multiple stop collars with up to 24 stops (per revolution) provide fractional	Super CB	5,000 (565)	5,000 (565)	750	AC or DC Solenoid
Accurate positioning for single or multiple stops	revolution capability.	Standard CB	5,000 (565)	5,000 (565)	1,800	AC or DC Solenoid

# Step 3

# Verify design function considerations

Once the appropriate series and model size have been determined, review the design considerations. A complete checklist of these and other options available are detailed in the How to Order section for each series.

# **Design Considerations**

### **All Models**

- □ CW or CCW rotation
- ☐ Single or multiple stop collar
- □ Bore size

### **Super CB and CB Series**

- ☐ AC or DC solenoid
- □ CB-5, CB-6, CB-8 and CB-10 available in the long life, Super CB Series (SCB). See pages 19–25 for specific details.

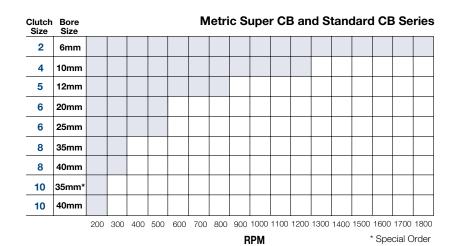
# **WSC Series**

- ☐ Hub input/shaft output or shaft input/hub output
- Overrunning Model O, start/ coast-to-stop Model SS or single revolution Model S

# **Selection Charts - RPM vs. Shaft Diameter**

Clutch Size	Bore Size				Sı	ıpeı	r CE	3 an	d S	tanc	dard	CB	Se	ries
2	1/4													
4	3/8													
5	1/2													
6	3/4													
6	1													
8	1*													
8	<b>1</b> <sup>1</sup> / <sub>4</sub>													
8	<b>1</b> <sup>3</sup> /8*													
8	<b>1</b> <sup>1</sup> / <sub>2</sub>													
10	<b>1</b> <sup>1</sup> / <sub>4</sub> *													
10	1 <sup>1</sup> / <sub>2</sub>													
10	<b>1</b> <sup>5</sup> /8*													
10	<b>1</b> <sup>3</sup> / <sub>4</sub>													

200 300 400 500 600 700 800 900 1000 1100 1200 1300 1400 1500 1600 1700 1800 \* Special Order \* Special Order



Clutch Bore **WSC Series** Size Size 1/4 2 3/8 4 5 1/2 3/4 6 6 1 8 1\* 1<sup>1</sup>/<sub>4</sub> 8 8 1<sup>3</sup>/8\* 8 11/2 200 300 400 500 600 700 800 900 1000 1100 1200 1300 1400 1500 1600 1700 1800

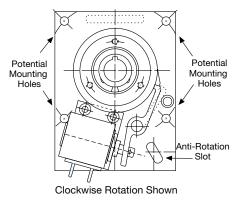
RPM \* Special Order

# **CB Mounting Requirements**

While Warner Electric wrap spring clutches are self-contained, packaged products, which are easy to mount, a few simple precautions should be taken to ensure maximum life.

All Warner Electric wrap spring clutch products are designed to be installed in parallel shaft applications where they are fully supported by the shaft on which they are mounted.

Each clutch/brake backing plate assembly has three or four mounting holes, plus an anti-rotation slot, and is designed to serve as a torque arm rather than as a rigid mounting plate. The plate should be restrained from rotating by a pin or shoulder bolt, while allowing for the plate to float axially. The anti-rotation device must be capable of withstanding the braking torque required by the load.



# Important: Do not rigidly mount unit. Plate must be allowed to "float" axially.

On CB type units, the input rotation is always connected to the input hub, and the output is always through the shaft through the hollow bore of the clutch/brake.

Connecting the unit to the parallel shaft may be accomplished by pinning (for sizes 4, 5 and 6 with 1 in. bore) or by key and set screw (for sizes 6 with 3/4 bore, 8 and 10). Size 2 uses a clamp collar.

When connecting the parallel shaft to the CB by using a belt, chain or gear drive, the input hub's radial bearing load capacity must not be exceeded. (See chart in next column). It may be necessary to counter bore or bearing mount the input pulley sprocket or gear.

# Maximum Radial Bearing Load at Maximum Speed

CB-2 = 7.5 lbs.

CB-4 = 14 lbs.

CB-5/Super CB-5 = 32 lbs.

CB-6/Super CB-6 = 63 lbs.

CB-8/Super CB-8 = 300 lbs.

CB-10/Super CB-10 = 500 lbs.

CB and Super CB style clutch/brakes are designed for horizontal shaft mounting. While it is possible to mount units vertically, vertically mounted units will see lower life than those mounted horizontally due to the wear between hubs resulting from gravity.

# **Horizontal Mounting**

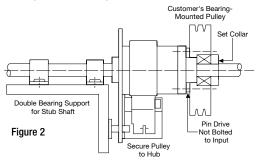
Figure 1 illustrates an ideal CB mounting. The unit is attached to the output shaft with both a key and set screws. The plate is restrained from rotating, but not from axial movement, reducing the side load on the CB's internal plate bearing.

In cases where easy access to the input is desirable, the clutch/brake can be mounted on a stub shaft. However, the unit must still be fully supported, while overhung loads on the input member must be avoided to maintain the life of the radial bearing.

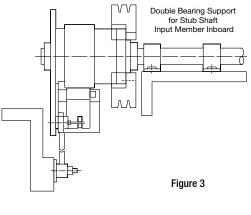
Customer's Input member counterbored to center mass over clutch bearing support on both ends

Figure 1 Plate restrained from rotating by pin or shoulder bolt. No axial binding.

Figures 2 and 3 illustrate alternate mounting configurations for achieving proper support. Inputs are usually face-mounted to the input hub of the CB unit as shown in Figure 1. This type of mounting is facilitated by the drilled and tapped holes provided in the free hub flange. The configuration shown in Figure 2 is a possibility, if the radial load on the input hub of the CB is small compared to the specified load.



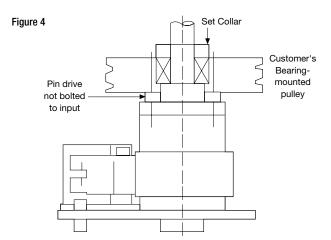
If the application contains a substantial radial bearing load, arrange the pulley over the centerline of the clutch free hub as illustrated in Figure 3. Place one support bearing as close to the pulley as possible, using a torque arm for anti-rotation.

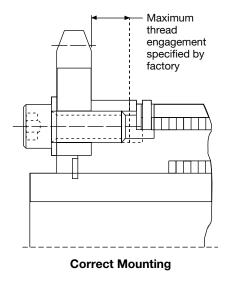


The smaller CB units (sizes 2, 4 and 5) have pilot holes in the output shaft, which guide drilling through the machine shaft for attaching the unit with a pin.

# **Vertical Mounting**

When it is necessary to mount a unit vertically, mount it so the input hub is oriented in the upward position as illustrated in Figure 4.

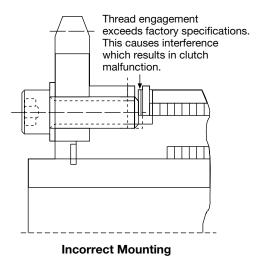




# **Thread Engagement Requirements**

Just a reminder . . . While mounting a sprocket or pulley to the input hub of your CB-2, CB-4, CB-5, CB-6, CB-8 or CB-10 the screws/bolts used must not protrude through the flange or hub. This will interfere or jam the control collar assembly, therefore causing the clutch to malfunction by failing to "drive" or causing the clutch to "slip." Please refer to the following chart for maximum thread engagement:

CB-2 = .150 in. CB-4 = .280 in. CB-5/Super CB-5 = .350 in. CB-6/Super CB-6 = .312 in. CB-8/Super CB-8 = .360 in. CB-10/Super CB-10 = .500 in.

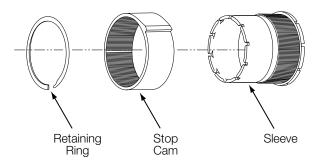


For further information and/or assistance, please call Warner Electric Technical Support at 800-825-9050.

# **CB Stop Collar Adjustment**

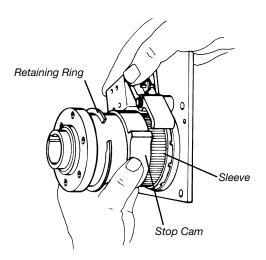
# **CB Stop Collar Adjustment**

Each CB and Super CB Series unit has an incrementally adjustable collar, which allows for changes to the output orientation.



To adjust the stop collar output orientation:

- Wrap the brake spring down completely by rotating the output shaft in the driving direction until it cannot travel any further;
- Remove the retaining ring from its groove and slide it forward on the sleeve; then,
- Hold the actuator clear, while sliding the stop cam off the sleeve. Rotate the cam to the desired stop position, and slide it back onto the sleeve; and,
- Slide the retaining ring back into position.



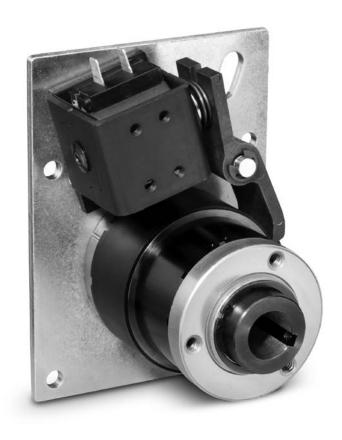
# **Adjustment Increments with Standard Stop Collars**

Infinitely Adjustable
2.4° Adjustable
1.8° Adjustable
1.8° Adjustable
1.6° Adjustable
1.5° Adjustable

# **Combination Clutch/Brake Packages**

CB Series clutch/brake combinations are designed for applications requiring a continuous rotational input being converted into starting and stopping a load. To start motion, the solenoid is pulsed, moving the actuator arm away from the control collar. This allows the clutch spring to wrap (wind) down onto the output assembly while the brake spring is unwinding, allowing the output to drive. Motion is stopped when the actuator returns to its rest position and the control collar rotates, stopping against the actuator. This forces the clutch spring to unwind releasing the input from the output and wraps the brake spring down, stopping the output. Anti-back and anti-overrun springs maintain position accuracy by eliminating any backward movement or bounce when stopped. The actual stopping position can be adjusted after installation by moving the splined cam of the control collar assembly.

The input hub is drilled and tapped to allow for mounting of sprockets, gears, sheaves, etc. The output is a hollow quill that mounts onto the customer's driven shaft. The backing plate is not a mounting plate. It must be held in place by a loose fit pin to eliminate any side or radial loads from preloading the unit's bearings.



### **Features**

- ☐ Stop Position Accuracy ±1/2°
- ☐ Adjustable Output Stop Positions
- ☐ Standard Features
  - CW or CCW Rotation
  - Hub Input Shaft Output
  - Anti-Overrun Output does not overrun Input
  - Anti-Back Output does not Backup
- ☐ 1, 2 and 4 stop collars for 360°, 180°, and 90° output increments standard
  - Special multi-stop collars also available (up to 24 stops)

- □ 115 VAC and 24 VDC Solenoids Standard
  - Other Voltages Available
- ☐ Dimensionally Interchangeable with Competitive Units
- □ 5 Standard Models

CB-2

CB-4

CB-5

CB-6

CB-8

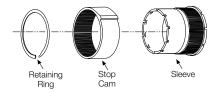
CB-10

# **CB Series Clutch / Brake**

Specifications	CB-2	CB-4	CB-5	CB-6	CB-8	CB-10
Static Torque	25 lb.in. (2.825 N-m)	120 lb.in. (13.56 N-m)	250 lb.in. (28.25 N-m)	500 lb.in. (56.5 N-m)	2,500 lb.in. (282.5 N-m)	5,000 lb.in. (565 N-m)
Maximum anti-overrun holding capability	10 lb.in. (1.13 N-m)	25 lb.in. (2.825 N-m)	45 lb.in. (5.085 N-m)	300 lb.in. (33.9 N-m)	600 lb.in. (67.8 N-m)	1,200 lb.in. (135 N-m)
Maximum anti-back holding capability	10 lb.in. (2.034 N-m)	80 lb.in. (9.04 N-m)	160 lb.in. (18.08 N-m)	300 lb.in. (33.9 N-m)	600 lb.in. (67.8 N-m)	1,200 lb.in. (135 N-m)
Inertia, rotating parts	.034 lb.in. <sup>2</sup>	.064 lb.in. <sup>2</sup>	.195 lb.in. <sup>2</sup>	1.718 lb.in. <sup>2</sup>	12.84 lb.in. <sup>2</sup>	48 lb.in. <sup>2</sup>
Maximum radial bearing load at maximum speed	7.5 lbs.	14 lbs.	32 lbs.	63 lbs.	300 lbs.	500 lbs.
Maximum operating speed	1,800 RPM	1,200 RPM	750 RPM	500 RPM	300 RPM	200 RPM
Response time, voltage on at full speed	20 MS	24 MS	27 MS	45 MS	50 MS	85 MS
Weight	1 lb.	2 lbs.	3 lbs.	7 lbs.	15 lbs.	29 lbs.

See page 36 for Minimum Inertia Requirements. See page 8 for Mounting Examples.

# **Control Collars**



These clutch/brakes (except CB-2) offer unique splined stop collars which can be adjusted radially in fine increments. This feature allows the user to reposition the output to comply with specified shaft and keyway placements. Standard stop collar positioning increments are shown below for all models:

CB-2	Infinitely Adjustable
CB-4	2.4° Adjustable
CB-5	1.8° Adjustable
CB-6	1.8° Adjustable
CB-8	1.6° Adjustable
CB-10	1.5° Adjustable

# Optional Multiple Stop Collars









A one, two or four stop collar is standard on CB Series clutch/brakes. A variety of stop collar configurations, up to 24 stops maximum, are available. Consult Warner Electric Technical Support at 800-825-9050 for complete information.

# **Basic Selection**

See pages 6–7 for basic product selection guidelines.

For complete Application Engineering information see pages 36-38.

### **How to Order**

Order by part number (see chart on dimensions page) or specify as follows.

# Specify:

1. Series CB: English Metric

2. Size: CB-2, CB-4, CB-5, CB-6, CB-8, CB-10

Direction of rotation:
 CW Clockwise
 CCW Counterclockwise

4. Coil voltage: 115 AC or 24 DC are standard 12 DC or 90 DC are options

5. Bore size:

 $CB-2 = \frac{1}{4}$ "  $CB-4 = \frac{3}{8}$ "  $CB-5 = \frac{1}{2}$ "  $CB-6 = \frac{3}{4}$ " or 1"

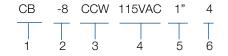
CB-8 = 11/4" or 11/2" standard 1" or 13/8" special order

CB-10 = 1½" or 1¾" standard 1¼" or 15%" special order

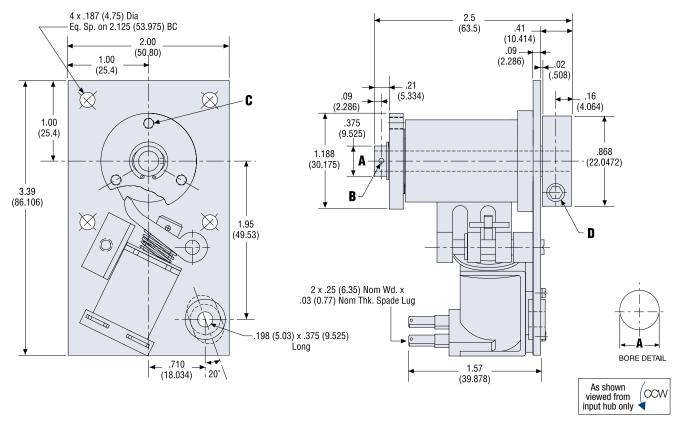
6. Stop collar:

1, 2 or 4 stops standard Other stop collars are available as specials

**Example:** CB-8, CCW, 115VAC, 1" bore, 4 stop collar



12 www.warnerelectric.com



# **Bore Sizes**

	Bore	Pin Hole	Mtg. Holes	Set Screws
	A	B	C	D
English in.	.251253	.062	3x #6-32 Eq. Sp.	#8
(mm)	(6.3655-6.4263)	(1.5748)	on .938 BC	SHCS
Metric mm	6.0 H9	1.5	3x M4 x 0.7 Eq. Sp.	M4 x 0.7
(in.)	(.23622374)	(.055–.062)	on 23.83 BC	SHCS

All dimensions are nominal unless otherwise noted.

# **CB-2 Part Numbers**

Bore				Stops	ı
Size	Voltage	Rotation	1	2	4
0.25"	24 VDC	CW CCW	302-17-001 302-27-001	302-17-002 302-27-011	302-17-003 302-27-003
0.25"	115 VAC	CW CCW	302-17-007 302-27-007	302-17-008 302-27-008	302-17-009 302-27-009

These are the most commonly requested parts – other voltages (such as 12VDC and 90VDC), bores and stop collars are available. See page 40 for metric part numbers.

# Electrical Data (±10%)

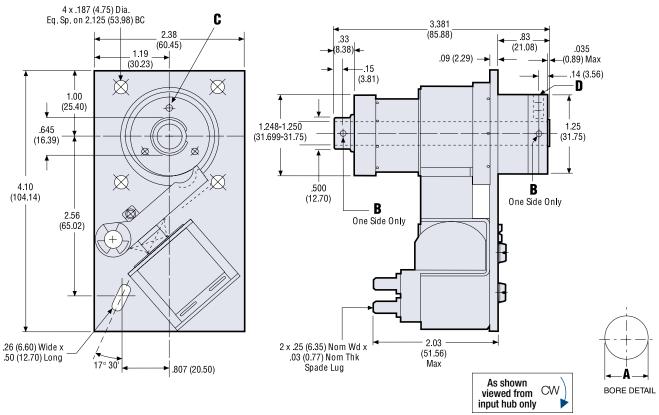
Voltage	Current (amps)	Resistance (ohms)	Status
115 AC 60 Hz	.10*	825	Standard
24 DC	.23	104	Standard
12 DC	.46	26	Option
90 DC	.06	1510	Option

<sup>(</sup>Coils are rated for continuous duty)

# **Specifications**

•	
Static Torque	25 lb.in.
Maximum anti-overrun holding capability	10 lb.in.
Maximum anti-back holding capability	10 lb.in.
Inertia, rotating parts	.034 lb.in. <sup>2</sup>
Maximum radial bearing load at maximum speed	7.5 lbs.
Maximum operating speed	1,800 RPM
Response time, voltage on at full speed	20 MS
Weight	1 lb.

<sup>\*115</sup> AC-In rush current .10 amps, Holding current .05 amps



# **Bore Sizes**

	Bore	Pin Hole	Mtg. Holes	Set Screws
	A	B	C	D
English in.	.376378	.125	3x #6-32 Eq. Sp.	#8-32 x .188
(mm)	(9.55-9.60)	(3.175)	on .938 BC	Lg. Hex Skt. Set Screw
Metric mm	10.0 H9	3.0	3x M4 x 0.7 on	M4 x 0.7 x 5.0
(in.)	(.39373951)	(.117121)	23.83 BC	Lg. Hex Skt. Set Screw

All dimensions are nominal unless otherwise noted.

# **CB-4 Part Numbers**

Bore				Stops	
Size	Voltage	Rotation	1	2	4
0.375"	24 VDC	CW CCW	304-17-001 304-27-001	304-17-011 304-27-007	304-17-007 304-27-026
0.375"	115 VAC	CW CCW	304-17-003 304-27-003	304-17-008 304-27-015	304-17-018 304-27-025

These are the most commonly requested parts – other voltages (such as 12VDC and 90VDC), bores and stop collars are available. See page 40 for metric part numbers.

# Electrical Data (±10%)

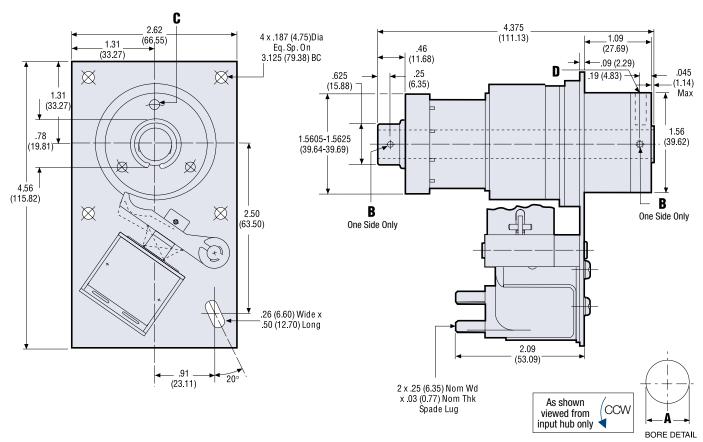
Voltage	Current (amps)	Resistance (ohms)	Status
115 AC 60 Hz	.10*	280	Standard
24 DC	.32	74	Standard
12 DC	.73	16.4	Option
90 DC	.10	936	Option

(Coils are rated for continuous duty)

# **Specifications**

opoonioationo	
Static Torque	120 lb.in.
Maximum anti-overrun holding capability	25 lb.in.
Maximum anti-back holding capability	80 lb.in.
Inertia, rotating parts	.064 lb.in. <sup>2</sup>
Maximum radial bearing load at maximum speed	14 lbs.
Maximum operating speed	1,200 RPM
Response time, voltage on at full speed	24 MS
Weight	2 lb.

<sup>\*115</sup> AC-In rush current .22 amps, Holding current .09 amps



# **Bore Sizes**

	Bore	Pin Hole	Mtg. Holes	Set Screws
	A	B	C	D
English in.	.50055025	.125	3x #10-32 UNF-2B	#8-32 x .25
(mm)	(12.712-12.764)	(3.175)	Eq. Sp. on 1.25 BC	Skt. Set Screw
Metric mm	12.0 H9	3.0	3x M5 x 0.8 on	
(in.)	(.47244741)	(.117121)	31.75 BC	

All dimensions are nominal unless otherwise noted.

# **CB-5 Part Numbers**

Bore				Stops	
Size	Voltage	Rotation	1	2	4
0.5"	24 VDC	CCW	305-17-001 305-27-001	305-17-002 305-27-002	305-17-003 305-27-003
0.5"	115 VAC	CW CCW	305-17-007 305-27-007	305-17-008 305-27-008	305-17-009 305-27-009

These are the most commonly requested parts – other voltages (such as 12VDC and 90VDC), bores and stop collars are available. See page 40 for metric part numbers.

# Electrical Data (±10%)

Voltage	Current (amps)	Resistance (ohms)	Status
115 AC 60 Hz	.10*	280	Standard
24 DC	.32	74	Standard
12 DC	.73	16.4	Option
90 DC	.10	936	Option

<sup>(</sup>Coils are rated for continuous duty)

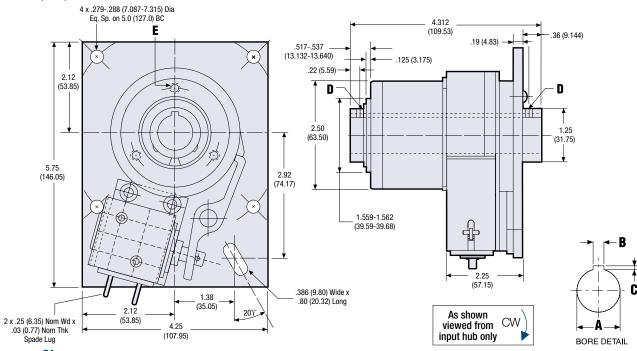
# **Specifications**

Static Torque	250 lb.in.
Maximum anti-overrun holding capability	45 lb.in.
Maximum anti-back holding capability	160 lb.in.
Inertia, rotating parts	.195 lb.in. <sup>2</sup>
Maximum radial bearing load at maximum speed	32 lbs.
Maximum operating speed	750 RPM
Response time, voltage on at full speed	27 MS
Weight	3 lb.

<sup>\*115</sup> AC-In rush current .22 amps, Holding current .09 amps

# **CB-6** Clutch / Brake

# **Dimensions** in. (mm)



# **Bore & Keyway Sizes**

	Bore	Keyway	Keyway	Set Screws/Pin Hole	Mtg. Holes
	A	Width B	Depth C	D	E
English in.	.75057525	.1875	.09375	2x #10-32 UNF-2B	3x #1/4-20 UNC-2B
(mm)	(19.062-19.114)	(4.7625)	(2.381)		Eq. Sp. on 2.062 BC
_	1.0005-1.0025 (25.412-25.464)	_	_	2x .187 Hole (4.7498)	3x #1/4-20 UNC-2B Eq. Sp. on 2.062 BC
Metric mm	20.0 H9	6.0	2.8	2x M5 x 0.8 x 5.0	3x M6 x 1.0 on
(in.)	(.78747894)	(.2362)	(.1102)	Lg. Hex Soc. Set Screw	52.38 BC
_	25.0 H9 (.98429862)	_	-	2x 5.0 Hole (.191203)	3x M6 x 1.0 on 52.38 BC

All dimensions are nominal unless otherwise noted.

# **CB-6 Part Numbers**

Bore				Stops	
Size	Voltage	Rotation	1	2	4
0.75"	24 VDC	CW CCW	306-17-051 306-27-029	306-17-074 306-27-046	306-17-162 306-27-134
0.75"	115 VAC	CW CCW	306-17-053 306-27-031	306-17-060 306-27-039	306-17-073 306-27-045
1.0"	24 VDC	CW CCW	306-17-057 306-27-032	306-17-061 306-27-147	306-17-031 306-27-150
1.0"	115 VAC	CW CCW	306-17-059 306-27-034	306-17-062 306-27-044	306-17-075 306-27-037

These are the most commonly requested parts – other voltages (such as 12VDC and 90VDC), bores and stop collars are available. See page 40 for metric part numbers.

# Electrical Data (±10%)

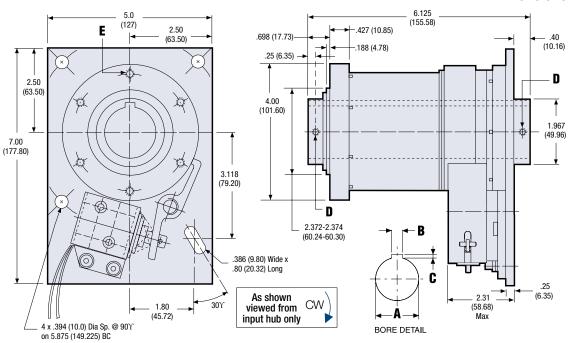
Voltage	Current (amps)	Resistance (ohms)	Status
115 AC 60 Hz	.33*	53.5	Standard
24 DC	.60	39.9	Standard
12 DC	1.15	10.4	Option
90 DC	.15	598	Option

<sup>(</sup>Coils are rated for continuous duty)

# **Specifications**

•	
Static Torque	500 lb.in.
Maximum anti-overrun holding capability	300 lb.in.
Maximum anti-back holding capability	300 lb.in.
Inertia, rotating parts	1.718 lb.in. <sup>2</sup>
Maximum radial bearing load at maximum speed	63 lbs.
Maximum operating speed	500 RPM
Response time, voltage on at full speed	45 MS
Weight	7 lb.

<sup>\*115</sup> AC-In rush current .62 amps, Holding current .31 amps



# **Bore & Keyway Sizes**

	Bore	Keyway	Keyway	Set Screws	Mtg. Holes
	A	Width B	Depth C	D	E
English in.	1.2505-1.2525	.3125	.15625	2x #1/4-20 UNC-2B	6x 5/16-18 UNC-2B
(mm)	(31.762-31.814)	(7.9375)	(3.9688)		Eq. Sp. on 3.375 BC
_	1.5005-1.5025 (38.112-38.164)	.375 (9.525)	.125 (3.175)	2x #1/4-20 x UNC-2B	6x 5/16-18 UNC-2B Eq. Sp. on 3.375 BC
Metric mm	35.0 H9	10.0	3.3	2x M6 x 1.0 x 10.0	6x M8 x 1.25 on
(in.)	(1.3780-1.3804)	(.3937)	(.1299)	Lg. Hex Soc. Set Screw	85.73 BC
_	40.0 H9 (1.5784-1.5772)	_	_	2x M6 x 1.0 x 10.0 Lg. Hex Soc. Set Screw	6x M8 x 1.25 on 85.73 BC

All dimensions are nominal unless otherwise noted.

# **CB-8 Part Numbers**

Bore				Stops	
Size	Voltage	Rotation	1	2	4
1.25"	24 VDC	CW CW	308-17-101 308-27-101	308-17-102 308-27-102	308-17-103 308-27-103
1.25"	115 VAC	CW CCW	308-17-107 308-27-107	308-17-108 308-27-108	308-17-109 308-27-109
1.5"	24 VDC	CW CW	308-17-119 308-27-119	308-17-120 308-27-120	308-17-121 308-27-121
1.5"	115 VAC	CCW	308-17-125 308-27-125	308-17-126 308-27-126	308-17-127 308-27-127

These are the most commonly requested parts – other voltages (such as 12VDC and 90VDC), bores and stop collars are available. See page 40 for metric part numbers.

# Electrical Data (±10%)

Voltage	Current (amps)	Resistance (ohms)	Status
115 AC 60 Hz	.33*	53.5	Standard
24 DC	.60	39.8	Standard
12 DC	1.15	10.4	Option
90 DC	.15	598	Option

<sup>(</sup>Coils are rated for continuous duty)

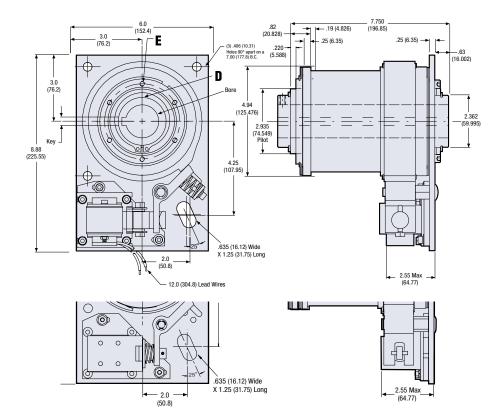
# **Specifications**

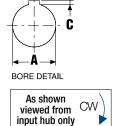
Specifications	
Static Torque	2,500 lb.in.
Maximum anti-overrun holding capability	600 lb.in.
Maximum anti-back holding capability	600 lb.in.
Inertia, rotating parts	12.840 lb.in. <sup>2</sup>
Maximum radial bearing load at maximum speed	300 lbs.
Maximum operating speed	300 RPM
Response time, voltage on at full speed	50 MS
Weight	15 lb.

<sup>\*115</sup> AC-In rush current .62 amps, Holding current .31 amps

# **CB-10 Clutch / Brake**

# **Dimensions** in. (mm)





# **Bore & Keyway Sizes\***

	Bore	Keyway	Keyway	Set Screws	Mtg. Holes
	A	Width B	Depth C	D	E
English in.	1.5005-1.503	.375	.187	#1/4-20 x UNC-2B	6x 1/4-20 UNC-2B
(mm)	(38.113-38.177)	(9.525)	(4.75)		Eq. Sp. on 3.417 BC
_	1.7505-1.753 (44.464-44.527)	.375 (9.525)	.187 (4.75)	#1/4-20 x UNC-2B	6x 1/4-20 UNC-2B Eq. Sp. on 3.417 BC
Metric mm	40.0 H9	12.0	4.0	M6 x 1.0 x 10.0	6x M8 x 1.25 on
(in.)	(1.5784-1.5772)	(.4724)	(.1574)	Lg. Hex Soc. Set Screw	86.79 BC

All dimensions are nominal unless otherwise noted. \* Optional Bores and Keys: 1.2505/1.2530 (31.7627/31.8262) for .3125 (7.9375) Sq Key 1.6255/1.6280 (41.2877/41.3512) for .375 (9.525) Sq Key

# **CB-10 Part Numbers**

Bore				Stops	
Size	Voltage	Rotation	1	2	4
1.5"	24 VDC	CW CCW	300-17-051 300-27-030	300-17-052 300-27-051	300-17-053 300-27-052
1.5"	115 VAC	CW CCW	300-12-033 300-22-033	300-12-051 300-22-047	300-12-044 300-22-041
1.75"	24 VDC	CW CCW	300-17-031 300-27-031	300-17-070	
1.75"	115 VAC	CW CCW	300-12-034 300-22-034	300-12-053 300-22-054	300-12-054 300-22-055

These are the most commonly requested parts – other voltages (such as 12VDC and 90VDC), bores and stop collars are available. See page 40 for metric part numbers.

# Electrical Data (±10%)

Voltage	Current (amps)	Resistance (ohms)	Status
115 AC 60 H	Hz .6*	11.5	Standard
24 DC	.94	25.4	Standard
12 DC	1.90	6.3	Option
90 DC	.24	378	Option

(Coils are rated for continuous duty)

# **Specifications**

•	
Static Torque	5,000 lb.in.
Maximum anti-overrun holding capability	1,200 lb.in.
Maximum anti-back holding capability	1,200 lb.in.
Inertia, rotating parts	48 lb.in. <sup>2</sup>
Maximum radial bearing load at maximum speed	500 lbs.
Maximum operating speed	200 RPM
Response time, voltage on at full speed	85 MS
Weight	29 lb.

<sup>\*115</sup> AC-In rush current 5.3 amps, Holding current .6 amps

# **Super CB Series Clutch / Brakes**

# **Long Life, High Performance Design**

The Super CB Series Clutch/Brakes function in the same manner as the standard CB Series. The major advantage of the Super CB Series is extraordinarily long life, up to five times longer than a standard unit. This makes the Super CB Series the ideal choice for applications involving high cycle rates and continuous heavy-duty operation.

# **Super CB Series design features**

The standard CB Series and SCB Series units both employ three primary hubs that are oil impregnated; the input hub, the brake hub and an internal hub pinned to the output shaft. On standard units, the oil lubricates the bearing surfaces of the input and brake hub, while the Super CB Series uses needle bearings in the input and brake hubs to increase the radial bearing load capacity. Both types require oil in the hubs to lubricate the springs. The Super CB Series units also feature hardened steel wear rings on the primary hubs at the crossover point of the clutch, brake and shaft hubs to further increase life. The control collar assemblies are glass reinforced nylon, strengthened by steel or aluminum inserts. The actuators are Delrin, AF on all models.



# **Features**

- ☐ Increased life-up to five times longer than standard models
- ☐ Stop Position Accuracy +1/2°
- ☐ Adjustable Output Stop Positions
- ☐ Standard Features
  - CW or CCW Rotation
  - Hub Input Shaft Output
  - Anti-Overrun Output does not overrun Input
  - Anti-Back Output does not Backup
- ☐ 1, 2 and 4 stop collars for 360°, 180°, and 90° output increments standard
  - Special multi-stop collars also available (up to 24 stops)

- ☐ 115 VAC and 24 VDC Solenoids Standard
  - Other Voltages Available
- ☐ Dimensionally Interchangeable with Competitive Units
- ☐ 4 Standard Models

SCB-5

SCB-6

SCB-8

- SCB-10
- ☐ High torque in small package☐ Actuating solenoid is AC or DC
  - operated
- ☐ Brake engages automatically when de-clutched

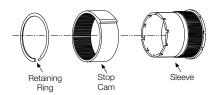
- □ Maintenance-free self-lubricating hubs are 18% oil by volume
- ☐ Hardened thrust washers on input and brake end
- ☐ Sintered metal hub offers easy machining for custom drive attachments
- ☐ Hardened and ground shaft
- ☐ Hub mounting holes for simple pulley or sprocket mounting
- ☐ Hardened crossover points on input, output and brake hubs provide increased life
- ☐ Steel tip insert on control cam collar
- ☐ Single or multi-stop collars available

# **Super CB Series Clutch / Brakes**

Specifications	SCB-5	SCB-6	SCB-8	SCB-10
Static Torque	250 lb.in. (28.25 N-m)	500 lb.in. (56.5 N-m)	2,500 lb.in. (282.5 N-m)	5,000 lb.in. (565 N-m)
Maximum anti-overrun holding capability	125 lb.in. (14.125 N-m)	300 lb.in. (33.9 N-m)	600 lb.in. (67.8 N-m)	1,200 lb.in. (135 N-m)
Maximum anti-back holding capability	125 lb.in. (14.125 N-m)	300 lb.in. (33.9 N-m)	600 lb.in. (67.8 N-m)	1,200 lb.in. (135 N-m)
Inertia, rotating parts	.236 lb.in. <sup>2</sup>	1.718 lb.in. <sup>2</sup>	12.840 lb.in. <sup>2</sup>	48 lb.in. <sup>2</sup>
Maximum radial bearing load at maximum speed	35 lbs.	65 lbs.	300 lbs.	500 lbs.
Maximum operating speed	750 RPM	500 RPM	300 RPM	200 RPM
Response time, voltage on at full speed	27 MS	45 MS	50 MS	85 MS
Weight	3 lbs.	7 lbs.	15 lbs.	29 lbs.

See page 36 for Minimum Inertia Requirements. See page 8 for Mounting Examples.

# **Control Collars**



These clutch/brakes offer unique splined stop collars which can be adjusted radially in fine increments. This feature allows the user to reposition the output to comply with specified shaft and keyway placements. Standard stop collar positioning increments are shown below for all models:

SCB-5	1.8° Adjustable
SCB-6	1.8° Adjustable
SCB-8	1.6° Adjustable
SCB-10	1.5° Adjustable

# **Optional Multiple Stop Collars**









A one, two or four stop collar is standard on SCB Series clutch/ brakes. A variety of stop collar configurations, up to 24\* stops maximum, are available. Consult Warner Electric Technical Support at 800-825-9050 for complete information.

\*Note: 4 stop maximum with steel tip cam.

# **Basic Selection**

See pages 6-7 for basic product selection guidelines.

For complete Application Engineering information see pages 36-38.

### **How to Order**

Order by part number (see chart on dimensions page) or specify as follows.

### Specify:

1. Series Super CB: English Metric

2. Size: SCB-5, SCB-6, SCB-8, SCB-10

3. Direction of rotation: CW Clockwise CCW Counterclockwise

4. Coil voltage: 115 AC or 24 DC are standard 12 DC or 90 DC are options

5. Bore size:

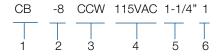
SCB-5: 1/2" standard SCB-6: 3/4", 1" standard SCB-8: 11/4". 11/2" standard 1", 13/8" special order  $SCB-10 = 1\frac{1}{2}$ " or  $1\frac{3}{4}$ " standard

11/4" or 15/8" special order

6. Stop collar:

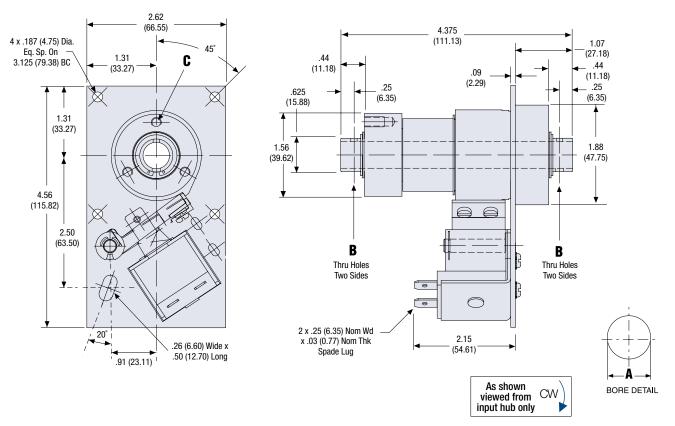
1, 2 or 4 stops standard Other stop collars are available as specials

Example: SCB-8, CCW, 115VAC, 1-1/4" bore, 1 stop collar.



# **Super CB-5 Clutch / Brake**

# **Dimensions** in. (mm)



# **Bore Sizes**

	Bore	Pin Hole	Mtg. Holes
	A	B	C
English in.	.50055025	.125	3x #10-32 UNF-2B
(mm)	(12.712-12.764)	(3.175)	Eq. Sp. on 1.25 BC
Metric mm	12.0 H9	3.0	3x M5 x 0.8 on
(in.)	(.47244741)	(.117121)	31.75 BC

All dimensions are nominal unless otherwise noted.

# **SCB-5 Part Numbers**

Bore Stops					
Size	Voltage	Rotation	1	2	4
0.5"	24 VDC	CW CCW	325-17-001 325-27-001	325-17-002 325-27-002	325-17-003 325-27-003
0.5"	115 VAC	CW CCW	325-17-004 325-27-004	325-17-005 325-27-005	325-17-006 325-27-006

These are the most commonly requested parts – other voltages (such as 12VDC and 90VDC), bores and stop collars are available. See page 40 for metric part numbers.

# Electrical Data (±10%)

Voltage	Current (amps)	Resistance (ohms)	Status	
115 AC 60 Hz	.10*	280	Standard	
24 DC	.32	74	Standard	
12 DC	.73	16.4	Option	
90 DC	.10	936	Option	

<sup>(</sup>Coils are rated for continuous duty)

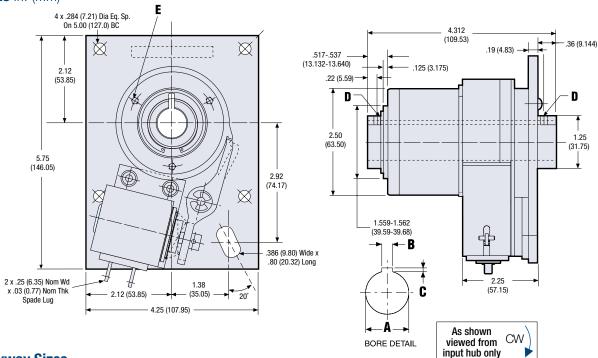
# **Specifications**

opcomoations	
Static Torque	250 lb.in.
Maximum anti-overrun holding capability	125 lb.in.
Maximum anti-back holding capability	125 lb.in.
Inertia, rotating parts	.236 lb.in. <sup>2</sup>
Maximum radial bearing load at maximum speed	35 lbs.
Maximum operating speed	750 RPM
Response time, voltage on at full speed	27 MS
Weight	3 lb.

<sup>\*115</sup> AC-In rush current .22 amps, Holding current .09 amps

# **Super CB-6 Clutch / Brake**

# **Dimensions** in. (mm)



# **Bore & Keyway Sizes**

	Bore	Keyway	Keyway	Set Screws/Pin Hole	Mtg. Holes
	A	Width B	Depth C	D	E
English in.	.75057525	.1875	.09375	2x #10-32 UNF-2B	3x #1/4-20 UNC-2B
(mm)	(19.062-19.114)	(4.7625)	(2.381)		Eq. Sp. on 2.062 BC
_	1.0005-1.0025 (25.412-25.464)	_	_	2x .187 Hole (4.7498)	3x #1/4-20 UNC-2B Eq. Sp. on 2.062 BC
Metric mm	20.0 H9	6.0	2.8	2x M5 x 0.8 x 5.0	3x M6 x 1.0 on
(in.)	(.78747894)	(.2362)	(.1102)	Lg. Hex Soc. Set Screw	52.38 BC
_	25.0 H9 (.98429862)	_	_	2x 5.0 Hole (.191203)	3x M6 x 1.0 on 52.38 BC

All dimensions are nominal unless otherwise noted.

# **SCB-6 Part Numbers**

Bore				Stops	
Size	Voltage	Rotation	1	2	4
0.75"	24 VDC	CW CCW	326-17-007 326-27-007	326-17-008 326-27-008	326-17-009 326-27-009
0.75"	115 VAC	CW CCW	326-17-019 326-27-019	326-17-020 326-27-020	326-17-021 326-27-021
1.0"	24 VDC	CW CCW	326-17-010 326-27-010	326-17-011 326-27-011	326-17-012 326-27-012
1.0"	115 VAC	CW CCW	326-17-022 326-27-022	326-17-023 326-27-023	326-17-024 326-27-024

These are the most commonly requested parts – other voltages (such as 12VDC and 90VDC), bores and stop collars are available. See page 40 for metric part numbers.

# Electrical Data (±10%)

Voltage	Current (amps)	Resistance (ohms)	Status
115 AC 60 Hz	.33*	53.5	Standard
24 DC	.60	39.8	Standard
12 DC	1.15	10.4	Option
90 DC	.15	598	Option

<sup>(</sup>Coils are rated for continuous duty)

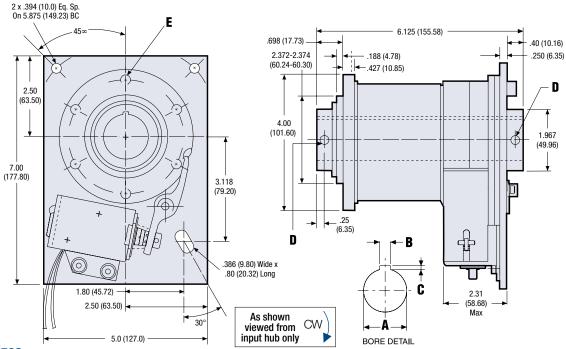
# **Specifications**

Static Torque	500 lb.in.
Maximum anti-overrun holding capability	300 lb.in.
Maximum anti-back holding capability	300 lb.in.
Inertia, rotating parts	1.718 lb.in. <sup>2</sup>
Maximum radial bearing load at maximum speed	65 lbs.
Maximum operating speed	500 RPM
Response time, voltage on at full speed	45 MS
Weight	7 lb.

<sup>\*115</sup> AC-In rush current .62 amps, Holding current .31 amps

# **Super CB-8 Clutch / Brake**

# **Dimensions** in. (mm)



# **Bore & Keyway Sizes**

	Bore	Keyway	Keyway	Set Screws	Mtg. Holes
	A	Width B	Depth C	D	E
English in.	1.2505-1.2525	.3125	.15625	2x #1/4-20 UNC-2B	6x 5/16-18 UNC-2B
(mm)	(31.762-31.814)	(7.9375)	(3.9688)		Eq. Sp. on 3.375 BC
_	1.5005-1.5025 (38.112-38.164)	.375 (9.525)	.125 (3.175)	2x #1/4-20 x UNC-2B	6x 5/16-18 UNC-2B Eq. Sp. on 3.375 BC
Metric mm	35.0 H9	10.0	3.3	2x M6 x 1.0 x 10.0	6x M8 x 1.25 on
(in.)	(1.3780-1.3804)	(.3937)	(.1299)	Lg. Hex Soc. Set Screw	85.73 BC
_	40.0 H9 (1.5784-1.5772)	_	_	2x M6 x 1.0 x 10.0 Lg. Hex Soc. Set Screw	6x M8 x 1.25 on 85.73 BC

All dimensions are nominal unless otherwise noted.

# **SCB-8 Part Numbers**

Bore				Stops	
Size	Voltage	Rotation	1	2	4
1.25"	24 VDC	CW CCW	328-17-019 328-27-019	328-17-020 328-27-020	328-17-021 328-27-021
1.25"	115 VAC	CW CCW	328-17-043 328-27-043	328-17-044 328-27-044	328-17-045 328-27-045
1.5"	24 VDC	CW CCW	328-17-013 328-27-013	328-17-014 328-27-014	328-17-015 328-27-015
1.5"	115 VAC	CCW	328-17-037 328-27-037	328-17-038 328-27-038	328-17-039 328-27-039

These are the most commonly requested parts – other voltages (such as 12VDC and 90VDC), bores and stop collars are available. See page 40 for metric part numbers.

# Electrical Data (±10%)

Voltage	Current (amps)	Resistance (ohms)	Status
115 AC 60 Hz	.33*	53.5	Standard
24 DC	.94	25.4	Standard
12 DC	1.87	6.43	Option
90 DC	.24	378	Option

<sup>(</sup>Coils are rated for continuous duty)

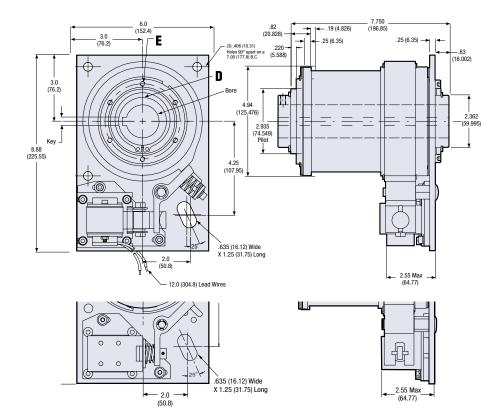
# **Specifications**

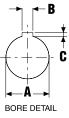
opoomoutono	
Static Torque	2,500 lb.in.
Maximum anti-overrun holding capability	600 lb.in.
Maximum anti-back holding capability	600 lb.in.
Inertia, rotating parts	12.840 lb.in. <sup>2</sup>
Maximum radial bearing load at maximum speed	300 lbs.
Maximum operating speed	300 RPM
Response time, voltage on at full speed	50 MS
Weight	15 lb.

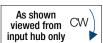
<sup>\*115</sup> AC-In rush current .62 amps, Holding current .31 amps

# **Super CB-10 Clutch / Brake**

# **Dimensions** in. (mm)







# **Bore & Keyway Sizes\***

	Bore	Keyway	Keyway	Set Screws	Mtg. Holes
	A	Width B	Depth C	D	E
English in.	1.5005-1.503	.375	.187	#1/4-20 x UNC-2B	6x 1/4-20 UNC-2B
(mm)	(38.113-38.177)	(9.525)	(4.75)		Eq. Sp. on 3.417 BC
_	1.7505-1.753 (44.464-44.527)	.375 (9.525)	.187 (4.75)	#1/4-20 x UNC-2B	6x 1/4-20 UNC-2B Eq. Sp. on 3.417 BC
Metric mm	40.0 H9	12.0	4.0	M6 x 1.0 x 10.0	6x M8 x 1.25 on
(in.)	(1.5784-1.5772)	(.4724)	(.1574)	Lg. Hex Soc. Set Screw	86.79 BC

All dimensions are nominal unless otherwise noted. \* Optional Bores and Keys: 1.2505/1.2530 (31.7627/31.8262) for .3125 (7.9375) Sq Key 1.6255/1.6280 (41.2877/41.3512) for .375 (9.525) Sq Key

# **SCB-10 Part Numbers**

Bore				Stops	
Size	Voltage	Rotation	1	2	4
1.50"	24 VDC	CW CCW	320-17-010 320-27-010	320-17-011 320-27-011	320-17-012 320-27-012
1.50"	115 VAC	CW CCW	320-12-001 320-22-001	320-12-002 320-22-002	320-12-003 320-22-003
1.75"	24 VDC	CW CCW	320-17-016 320-27-016		
1.75"	115 VAC	CCW	320-12-007 320-22-007	320-12-008 320-22-014	

These are the most commonly requested parts – other voltages (such as 12VDC and 90VDC), bores and stop collars are available. See page 40 for metric part numbers.

# Electrical Data (±10%)

Voltage	Current (amps)	Resistance (ohms)	Status
115 AC 60 Hz	.6*	11.5	Standard
24 DC	.94	25.4	Standard
12 DC	1.90	6.3	Option
90 DC	.24	378	Option

(Coils are rated for continuous duty)

\*115 AC-In rush current 5.3 amps, Holding current .6 amps

# **Specifications**

Static Torque	5,000 lb.in.
Maximum anti-overrun holding capability	1,200 lb.in.
Maximum anti-back holding capability	1,200 lb.in.
Inertia, rotating parts	48 lb.in. <sup>2</sup>
Maximum radial bearing load at maximum speed	500 lbs.
Maximum operating speed	200 RPM
Response time, voltage on at full speed	85 MS
Weight	29 lb.

Designed to meet the rigorous demands of baggage handling conveyor diverters. Confined space for the drive system on the HSD (High Speed Diverter) dictate the wrap spring clutch-brake is vertically mounted with the input down. The AB (anti-backup) spring is removed to allow the paddles to be moved backward when luggage is jammed or caught between paddles.

Problems caused by this design criteria: removal of the AB spring and the weight of the timing pulley.

The other function of the AB spring is to keep the clutch spring unwound when the input is idling. The clutch spring can drag and overheat the input hub.

If the OEM bronze washer is missing or wears, the full weight of the pulley is supported by a snap ring that will wear into the pilot washer. Hubs will separate, then the AOR (anti-overrun) can unwind, and/or the brake spring up tang moves out of position in collar.

### **Features**

- ☐ Thrust bearing supports weight of input timing pulley
- ☐ Oil reservoir wick
- ☐ Two teflon coated input collar washer
- ☐ Input hub dual row spread needle bearings
- ☐ Collar is aircraft grade aluminum
- ☐ Solid actuator link
- □ Large diameter actuator post
- □ Dimensional replacement for OEM product



# **SCB-10 Part Numbers**

Model Number	Voltage	Part Number	Stops
CW	115 VAC	320-12-018A	1
CCW	115 VAC	320-22-020A	1
CW	220 VAC	320-12-019	1
CCW	220 VAC	320-22-021	1

Note; 300-12-072 (2-stop CW) older style does not have upgrades

# **For Airport Baggage Handling Conveyor Diverters**



# **Improvements**

# Thrust bearing supports weight of input timing pulley

- Eliminates bronze thrust washer
- Less heat is generated by thrust bearing versus friction from bronze washer
- Eliminates retaining ring wear into pilot washer

# Oil reservoir wick in AB pocket

- Reservoir wick allows additional oil flow capacity into hubs

### Two teflon coated input collar washers

- One tabbed to move with collar and other moves with input hub
- OEM has one washer that rotates with input hub wearing against large retaining ring and collar can drop
- More rigid versus single

### Collar aluminum aircraft grade

- Versions of OEM design have sheet metal plates spiral clamped to collar
- Others have aluminum ring glued to plastic collar

### Solid solenoid actuator link

 OEM uses pin that breaks or falls out due to high impact from solenoid

### Fasteners that secure solenoid are #10

- #8 on OEM - more strength to withstand solenoid impact

# **WSC Series Clutches**

# **Mechanically Activated, Basic Wrap Spring Clutch Design**

WSC Series wrap spring clutches are mechanically actuated, eliminating the need for external electrical control devices. These simple, trouble free, easy-to-install clutches feature a high torque capacity in a small, compact package.

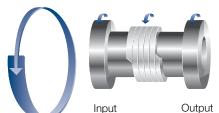
A choice of three different operating styles is available.

# **Features**

- ☐ Five standard sizes
- ☐ Standard bore sizes from 1/4" to 1-1/2"
- ☐ Static torque rating from 25 lb.in. to 2500 lb.in.
- ☐ Mechanically actuated
- ☐ Choice of hub or shaft input
- ☐ 1, 2 or 4 stop collars standard
- □ Overtravel stop Special
- ☐ Anti-overrun Special
- ☐ Adjustable stop feature Special
- ☐ Self-lubricating, no maintenance
- ☐ Simple mechanical actuation
- ☐ Easy-to-machine hubs readily adapt to application needs
- ☐ Single stop collars for single revolution operation multistops for less than one turn



### Overrunning/One-Way (Model O)

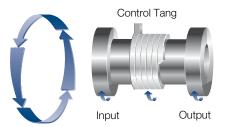


The overrunning clutch (Model O) transmits torque up to the rated value in the positive direction, when dispergaged it only transmits some drag.

disengaged it only transmits some drag torque in the reverse direction. Major applications for this unit are anti-overrun protection and anti-backup devices.

The load is allowed to overrun the input, should the load speed exceed the input speed. In reverse it acts as a one-way clutch, preventing reverse rotation.

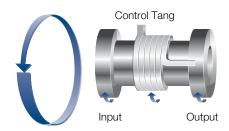
### Start/Coast-To-Stop (Model SS)



The start/coast-to-stop clutch (Model SS) accelerates the load just after the control collar has been released, thus the collar is free to rotate allowing the spring to grip both hubs together. To disconnect the clutch, the collar has to be restrained, stopping the collar from rotating via the stop face. The spring will then be opened and the clutch will be disengaged. The output is free to rotate and will be stopped by system friction and clutch drag torque.

The start/coast-to-stop clutch is engaged until the collar is stopped, which disengages the clutch allowing the load to coast to a stop.

### Single Revolution (Model S)



The single revolution clutch (Model S) accelerates in the same manner as the model SS. The deceleration starts when the collar is restrained, and the spring is opened, disengaging the clutch.

For Model S, the brake torque capability is limited to 10% of the rated torque.

All WSC Series clutches are easy to install. The shaft can be pinned or, on larger units, delivered with keyways, a simple solution for applications requiring accurate positioning. One, two or four stop per revolution collars are available.

Specifications	WSC-2	WSC-4	WSC-5	WSC-6	WSC-8
Static Torque (lb.in.)	25	120	250	500	2500
Inertia, shaft input rotating parts (lb.in.²)	0.006	0.015	0.059	0.570	4.99
Inertia, hub input rotating parts (lb.in.²)	0.008	0.023	0.069	0.73 (0.75" Bore) 0.68 (1.00" Bore)	11.91 (1.25" Bore) 11.60 (1.50" Bore)
Maximum radial bearing load at maximum speed (lbs.)	6.75	13.5	31.5	63.0	300.0
Maximum operating speed (RPM)	1800	1200	750	500	300
Weight (lbs.)	0.13	0.22	0.62	2.60	8.25

See page 36 for Minimum Inertia Requirements.

See page 8 for Mounting Examples.

# Optional Multiple Stop Collars









The WSC Series clutches feature a choice of collars with one, two or four stops as standard. Other stop collar configurations are available on special order.

# **Basic Selection**

See pages 6–7 for basic product selection guidelines.

For complete Application Engineering information see pages 36–38.

# **How to Order**

Order by part number (see chart on dimensions page) or specify as follows.

# Specify:

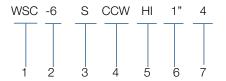
- 1. WSC Series
- 2. Size: WSC-2, WSC-4, WSC-5, WSC-6, or WSC-8
- 3. Type of Operation:
  - S—Single revolution
  - SS-Start/Coast-To-Stop
  - O-Overrunning
- 4. Direction of rotation:
  - CW Clockwise
  - CCW Counterclockwise
  - (Direction of rotation is determined from
  - the perspective of the input end.)
- 5. Hub input (HI) or shaft input (SI)
- 6. Standard Bore size:
  - WSC-2 = 1/4"
  - WSC-4 = 3/8"
  - WSC-5 =  $\frac{1}{2}$ "
  - WSC-6 =  $\frac{3}{4}$ " or 1"
  - WSC-8 = 11/4" or 11/2"

7. Stop collar:

Standard Stops: 1, 2 or 4

Example: WSC-6, S, CCW, HI,

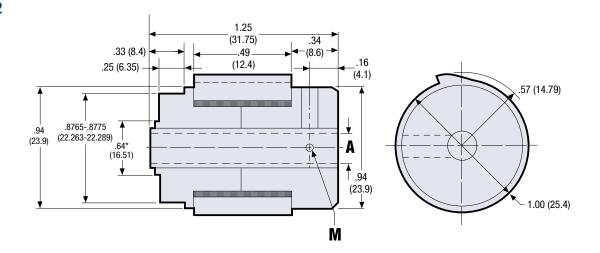
1" bore, 4 stop collar.



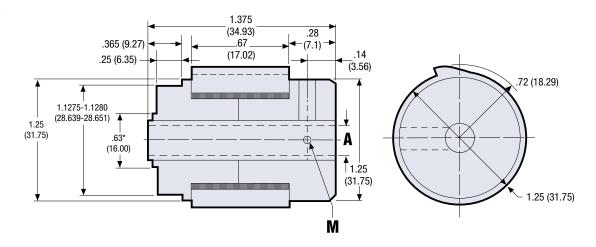
# WSC-2, WSC-4, WSC-5 Clutches

# **Dimensions** in. (mm)

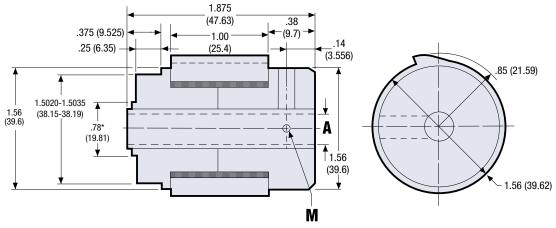
# WSC-2



# WSC-4



# **WSC-5**



\*Retaining ring clearance diameter

# **WSC Part Numbers**

# **WSC-2**

Bore					Stop	os	
Size	Operation	Rotation	Input	None	1	2	4
0.25"	S (start/stop)	CW	Hub	_ _	202-10-016 202-20-016	202-10-009 202-20-015	202-10-020 202-20-017
0.25"	S (start/stop)	CCW	Shaft	_ _	202-30-011 202-40-014	202-30-007 202-40-008	202-30-015 202-40-017
0.25"	O (overrunning)	CW CCW	Hub/Shaft	202-10-018 202-20-019	_ _	_ _	_ _

These are the most commonly requested parts. Other units offering overrunning or start/coast-to-stop operation are available.

# WSC-4

Bore					Sto	os	
Size	Operation	Rotation	Input	None	1	2	4
0.375"	S (start/stop)	CCW	Hub	_ _	204-10-001 204-20-004	204-10-016 204-20-008	204-10-010 204-20-016
0.375"	S (start/stop)	CW CCW	Shaft	_ _	204-30-001 204-40-001	204-30-007 204-40-006	204-30-009 204-40-012
0.375"	O (overrunning)	CW CCW	Hub/Shaft	204-10-003 204-20-003	_ _	_ _	_ _

These are the most commonly requested parts. Other units offering overrunning or start/coast-to-stop operation are available.

# WSC-5

Bore					Sto	pps	
Size	Operation	Rotation	Input	None	1	2	4
0.5"	S (start/stop)	CCW	Hub	_ _	205-10-001 205-20-001	205-10-014 205-20-006	205-10-017 205-20-011
0.5"	S (start/stop)	CW CCW	Shaft		205-30-001 205-40-004	205-30-014 205-40-016	205-30-016 205-40-007
0.5"	O (overrunning)	CW CCW	Hub/Shaft	205-10-003 205-20-003			

These are the most commonly requested parts. Other units offering overrunning or start/coast-to-stop operation are available.

# **Bore Data**

Model	Bore A	M
WSC-2	.25052530 (6.363-6.426)	#8-32
WSC-4	.376378 (9.551-9.601)	.125 dia. (3.175 dia.)
WSC-5	.501504 (12.726-12.802)	.187 dia. (4.75 dia.)

# **Specifications**

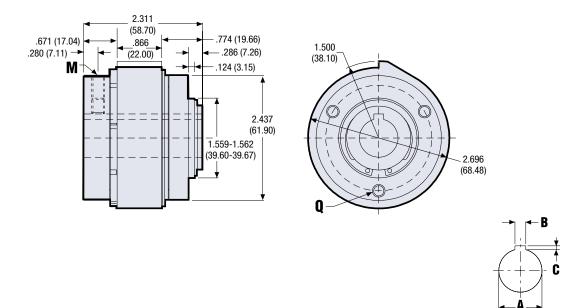
	WSC-2	WSC-4	WSC-5	
Static Torque (lb.in.)	25	120	250	
Inertia, shaft input rotating parts (lb.in.²)	0.006	0.015	0.059	
Inertia, hub input rotating parts (lb.in.²)	0.008	0.023	0.069	
Maximum radial bearing load at maximum speed (lbs.)	6.75	13.5	31.5	
Maximum operating speed (RPM)	1500	1200	750	
Weight (lbs.)	0.13	0.22	0.62	_

All dimensions are nominal unless otherwise noted.

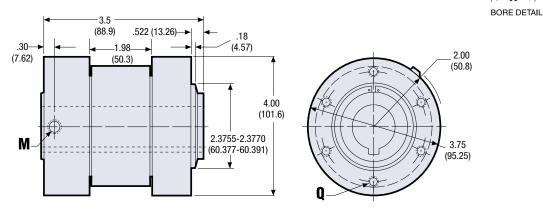
# **WSC-6, WSC-8 Clutches**

# **Dimensions** in. (mm)

# WSC-6



# WSC-8



# **Bore & Keyway Sizes**

	Bore A	Keyway Width B	Keyway Height C	М	Q
WSC-6	.75107525 (19.076-19.114)	.1885 (4.788)	.09375 (2.381)	#1/4-20 Tap	3x #1/4-20 Tap on 2.062 (52.375) BC Max. Thread Engagement .310 (7.87)
WSC-6	1.0010-1.0025 (25.426-25.464)	_	_	#1/4-20 Tap	3x #1/4-20 Tap on 2.062 (52.375) BC Max. Thread Engagement .310 (7.87)
WSC-8	1.2510-1.2525 (31.776-31.814)	.3125 (7.9375)	.15625 (3.9688)	#3/8-16 Tap	6x 5/16-18 on 3.375 (85.725) BC Max. Thread Engagement .375 (9.53)
WSC-8	1.5010-1.5025 (38.126-38.164)	.375 (9.525)	.125 (3.175)	#3/8-16 Tap	6x 5/16-18 on 3.375 (85.725) BC Max. Thread Engagement .375 (9.53)

All dimensions are nominal unless otherwise noted.

# **Part Numbers**

# WSC-6

Bore					Stop	os	
Size	Operation	Rotation	Input	None	1	2	4
0.75"	S (start/stop)	CW	Hub	_	206-10-002	206-10-062	206-10-064
		CCW		_	206-20-002	206-20-023	206-20-058
0.75"	S (start/stop)	CW	Shaft	_	206-30-011	206-30-052	206-30-025
		CCW		_	206-40-002	206-40-014	206-40-020
0.75"	O (overrunning)	CCW CCW	Hub/Shaft	206-10-008 206-20-008	_ _	_ _	_ _
1.0"	S (start/stop)	CW	Hub	_	206-10-003	206-10-057	206-10-059
		CCW		_	206-20-003	206-20-060	206-20-013
1.0"	S (start/stop)	CW	Shaft	_	206-30-003	206-30-051	206-30-056
		CCW		_	206-40-013	206-40-023	206-40-025
1.0"	O (overrunning)	CW CCW	Hub/Shaft	206-10-009 206-20-009	_ _	_ _	_ _

These are the most commonly requested parts. Other units offering overrunning or start/coast-to-stop operation are available.

# **WSC-8**

Bore					Stop	os	
Size	Operation	Rotation	Input	None	1	2	4
1.25"	S (start/stop)	CW	Hub	_	208-10-004	208-10-027	208-10-028
		CCW		_	208-20-001	208-20-028	208-20-030
1.25"	S (start/stop)	CW	Shaft	_	208-30-001	208-30-021	
		CCW		_	208-40-013	208-40-015	208-40-017
1.25"	O (overrunning)	CW CCW	Hub/Shaft	208-10-006 208-20-007			
1.50"	S (start/stop)	CW	Hub	_	208-10-007	208-10-025	208-10-030
		CCW		_	208-20-003	208-20-032	208-20-021
1.50"	S (start/stop)	CW	Shaft	_	208-30-003	208-30-025	208-30-027
		CCW		_	208-40-003	208-40-020	208-40-022
1.50"	O (overrunning)	CW CCW	Hub/Shaft	208-10-009 208-20-009			

These are the most commonly requested parts. Other units offering overrunning or start/coast-to-stop operation are available.

# **Specifications**

•		
	WSC-6	WSC-8
Static Torque (lb.in.)	500	2500
Inertia, shaft input rotating parts (lb.in.²)	0.570	4.99
Inertia, hub input rotating parts (lb.in.²) Bore)	0.73 (0.75" Bore) 0.68 (1.00" Bore)	11.91 (1.25" Bore) 11.60 (1.50"
Maximum radial bearing load at maximum speed (lbs.)	63	300
Maximum operating speed (RPM)	500	300
Weight (lbs.)	2.60	8.25

# **Power Supply Units**

# One Shot Octal Socket Power Supply Model WSCC-102

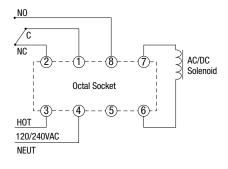
Warner Electric's One Shot Power Supply is a plug-in clutch/brake control designed for operation of AC or DC wrap spring clutches and brakes with a D-frame coil. The One Shot provides a single voltage pulse of 160 or 325 VDC for approximately 20MS, whether the customer supplied switch is momentarily closed or held closed.

The One Shot Power Supply is UL Listed when used with Warner Electric's octal socket, part no. 6001-101-001, or DIN rail mount octal socket, part no. 6001-101-002 (each purchased separately) and only UL-Recognized when used with other sockets. This unit may be mounted in any convenient position using the two mounting holes provided on the socket.

Actuating the single pole, double throw (SPDT) switch energizes the solenoid coil. Releasing or resetting the switch charges an internal capacitor. A minimum of 20 milliseconds cycle time is required between operations.

**Note:** Designed for use with actuator limit stop option.

# **Connection Diagram**





One Shot Octal Socket Control P/N 901-00-019

# **Specifications**

**Input:** 120/240 VAC, 50/60 Hz

Output: 160/290 VDC Peak, 3 amps max at 160 VDC output,

5 amps max. at 290 VDC ouput

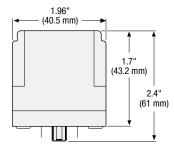
**Ambient Temperature:** + 32° F to + 122° F

0° C to + 50° C

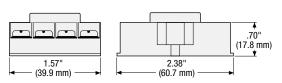
For use with D-Frame coils only.

Solenoid	VAC Input	Maximum Cycle Rate
12 VDC	120 240	200 CPM 35 CPM
24 VDC	120 240	300 CPM 40 CPM
90 VDC	120 240	400 CPM 60 CPM
115 VAC	120 240	350 CPM 45 CPM

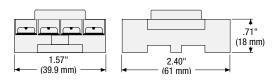
# **Dimensions** in. (mm)



One Shot Control PN 901-00-019



Octal Socket P/N 6001-101-001



DIN Rail Mount 05 P/N 6001-101-002

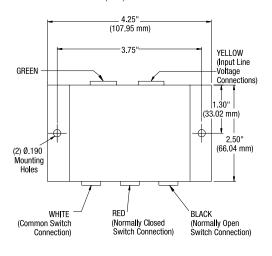
# One Shot Power Supply Model WSCC-101

The One Shot Power Supply is available for use with standard AC as well as DC D-Frame coils. The one shot provides a single overexcite voltage pulse whether the switch is momentarily closed, or held closed. The unit operates on either 120 or 230 AC, 50/60 Hz power and may be mounted in any convenient position by use of two mounting holes for #8-32 screws.

**Note:** Designed for use with actuator limit stop option and D-Frame coil.

# CLUTCH 120/240 VAC 50/60 HZ. WARNER ELECTRIC WARNER SUPPLY ONE SHOT POWER SUPPLY ONE SHOT POWER CLUTCH FOR WRAP SPRING CLUTCH WSCC-101 901-00-014 1NPUT: 120/240 VAC 50/60 HZ OUTPUT: 160 VDC, PEAK N.C. N.C.

# Dimensions in. (mm)





# **Specifications**

**Input:** 120/240 VAC, 50/60Hz

Output: 160/290 VDC Peak, 3 amps max at 160 VDC output,

5 amps max at 290 VDC output

**Ambient Temperature:** +32°F to +122°F

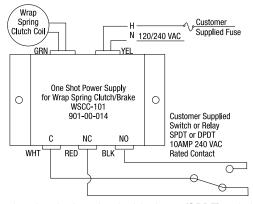
0°C to +50°C

Terminals: Amp Inc., Fast-on 250 Series Tabs (.250 X .032),

For 14-16AWG AMP #640905-1 For 18-22AWG AMP #640903-1

Solenoid	VAC Input	Maximum Cycle Rate
12 VDC	120 240	200 CPM 35 CPM
24 VDC	120 240	300 CPM 40 CPM
90 VDC	120 240	400 CPM 60 CPM
115 VAC	120 240	350 CPM 45 CPM

# **Connection Diagram**



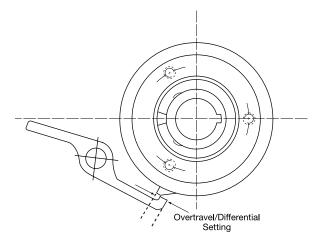
Actuating the single pole, double throw (SPDT) switch energizes the solenoid coil. Releasing or resetting the switch charges an internal capacitor. A minimum of 20 milliseconds cycle time is required between operations.

# **CB Spring Differential Setting**

# **CB Spring Differential Setting**

All CB and Super CB Series clutch/brakes are factory-set to the proper spring differential overtravel. If a spring must be replaced, prior to disassembly, make sure the two spring tang slots are marked to help ensure proper reassembly. (There should be punch marks from the factory on either side of the spring tang slots marking those used for the correct differential setting.) If the slots are unmarked and the unit has been disassembled, use the following procedure to reset the spring differential.

- 1. Remove the retaining ring from the input hub.
- 2. Rotate the clutch so the brake spring is fully wrapped down by rotating the output shaft in the driving direction until it cannot travel any farther.
- 3. With the brake fully engaged (per step 2), pull the input hub assembly out, and pull the clutch spring tang out of its slot, allowing it to jump to wherever it comes to rest.
- 4. Unwrap the clutch spring and push it backwards into the nearest slot.
- 5. Push the input hub back into place, release the actuator, and rotate the clutch until the brake spring fully wraps down again.
- With the brake fully engaged (wrapped down per step 2), hold the shaft with one hand and release the actuator. The stop collar will rotate forward as the brake is released and the clutch engages.



Measure the overtravel, use calipers to measure the distance between the tip of the actuator, and the tip of the stop on the cam.

# The Amount of Acceptable Overtravel Varies with the Size of the Unit

CB-2	.09 to .19"
CB-4	.09 to .19"
CB-5/Super CB-5	.09 to .19"
CB-6/Super CB-6	.22 to .38"
CB-8/Super CB-8	.39 to .60"
CB-10/Super CB-10	.60 to .75"

- 8. If the overtravel measurement is within these specified limits, reinstall the retaining ring and the unit's overtravel is reset.
- 9 A. If the overtravel exceeds the specified limit, move the brake spring backwards one slot (against the direction of rotation) and repeat steps two through seven.
  - B. If the overtravel is less than the specified limit, move the brake spring forward one slot (in the direction of rotation,) and repeat steps two through seven.

# **If Spring Replacement Is Not Required**

If the unit is disassembled and the drive and/or brake springs do not need to be replaced, proceed as follows:

- Reposition the drive and brake springs into their original positions onto the output shaft assembly.
- Reassemble the clutch, and position the spring tangs of the drive and brake springs in the factory marked locations on the control collar assembly (on the control collar, the designated tang slots are indicated with punch marks on either side of each slot).
- After the unit is completely reassembled, the differential setting should match that of the original factory setting.

# **CB Actuator Gap Adjustment**

Actuator gap is factory set and does not require adjustment at installation, only when replacing solenoids.

Push collar sleeve toward actuator while bottoming plunger into solenoid. Do not push on actuator.

Adjust gap to .020 / .030 inch for all sizes except CB-10 gap .040 / .060 inch.

**Note:** If a multiple stop the cam height will vary, measure over the highest cam.

Tighten solenoid adjustment screws. Measure gap to verify .020 / .030 inch, readjust if required.

 $\label{eq:Note: AC - Solenoids - If plunger does not bottom in solenoid it will overheat when energized.}$ 

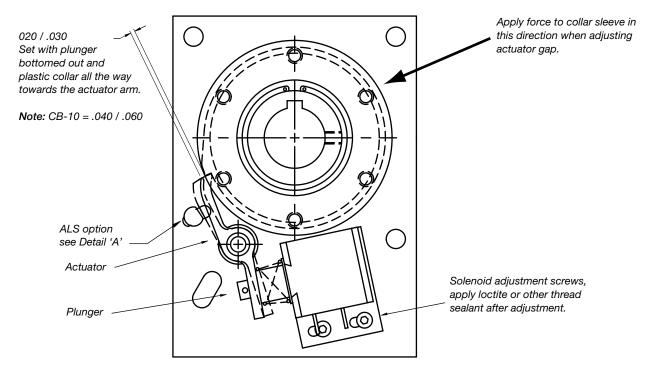
Tighten solenoid adjustment screws. Measure gap to verify .020 / .030 inch, readjust if required.

**Note:** AC - Solenoids — If plunger does not bottom in solenoid it will overheat when energized.

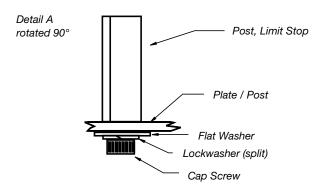
### **Optional Actuator Limit Stop (ALS)**

After setting gap with plunger bottomed in solenoid, slide limit stop post in slot until it comes in contact with back of actuator and does not reduce the actuator gap. Move post slightly away from actuator, tighten and verify gap is correct. Sizes 4 and 6 have an eccentric bar that is rotated to adjust.

# CB-8 Shown - Layout of unit and optional ALS will vary by size



# Optional ALS (Actuator Limit Stop) style will vary by size



# **Application Engineering**

# **Selection Considerations**

# **Application Analysis**

### 1. Function

The process for establishing the clutch or brake function is illustrated in Step 1 on page 6. In review, the three functions and the appropriate series selections are noted below.

# Overrunning (One Way Clutch)

Unidirectional torque transmission with free wheeling in opposite direction.

### Selection

WSC (Model O)

### Start/Coast-to-Stop (Random Positioning)

Engage/disengage with random stop position.

### Selection

WSC (Model SS)

### Start/Stop (Single Revolution)

Accurate stop position in single or fraction revolution cycles.

### Selection

WSC (Model S) Standard CB Super CB

### 2. Calculate load inertia (WR2)

Use the inertia chart on page 37 to determine the inertia of the application components. To determine WR² of a given shaft or disc, multiply the WR² from the chart by the length of shaft or thickness of disc in inches. Note: For hollow shafts, subtract WR² of the I.D. from the WR² of the O.D. and multiply by length.

In order to calculate the inertias of components which are made of material other than steel, use the multipliers found in the conversion chart (right) to establish the inertias of these components.

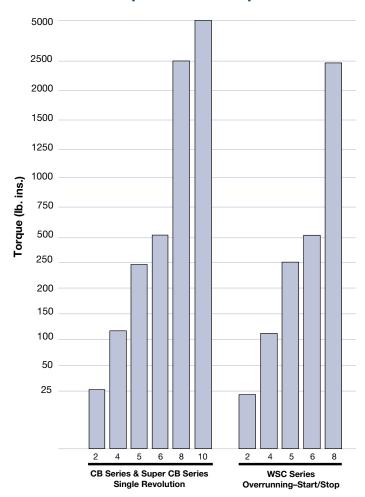
For applications involving machined parts or reflected rotational or linear inertia, please refer to the inertia discussion in the Application Engineering section of Warner Electric's Packaged Electromagnetic Clutches/Brakes Catalog, P-1234.

### **Inertia Conversion Chart**

In order to determine the inertia of a rotating member (shaft, disc, etc.) of a material other than steel, multiply the inertia of the appropriate steel diameter from the chart on page 37 by:

Material	Multiplier
Bronze	1.05
Steel	1.00
Iron	.92
Powdered Metal Bronze	.79
Powdered Metal Iron	.88
Aluminum	.35
Nylon	.17

# **Torque vs. Model Comparison**



**Series and Model** 

66.816 77.04 87.984 100.656 113.904 128.88 144 162.72 182.88 203.04 223.2 252 277.92 306.72 338.4 371.52 407.52 444.96 486.72 529.92 576 626.4 679.68 735.84

# **Selection Considerations**

# **Inertia of Steel Shafting** (Per Inch of Length or Thickness)

ilei ila vi Steel	Silaiting (Per Inch of Length	th or Thickness)
Dia. (in.)	WR² (lb.in.²)	Dia. (in.)
1/4	.00011	7
3/8	.00055	7-1/4
1/2	.00173	7-1/2
3/4	.00864	7-3/4
1	.0288	8
1-1/4	.072	8-1/4
1-1/2	.144	8-1/2
1-3/4	.288	8-3/4
2	.432	9
2-1/4	.72	9-1/4
2-1/2	1.152	9-1/2
2-3/4	1.584	9-3/4
3	2.304	10
3-1/2	4.176	10-1/4
3-3/4	5.472	10-1/2
4	7.056	10-3/4
4-1/4	9.072	11
4-1/2	11.376	11-1/4
5	17.28	11-1/2
5-1/2	25.488	11-3/4
6	36	12
6-1/4	42.624	12-1/4
6-1/2	49.68	12-1/2
6-3/4	57.888	12-3/4

Dia. (in.)	WR² (lb.in.²)
13	803.52
13-1/4	858.24
13-1/2	924.48
13-3/4	995.04
14	1068.48
14-1/4	1147.68
14-1/2	1229.75
14-3/4	1317.6
15	1404
16	1815.84
17	2314.08
18	2910.24
19	3611.52
20	4433.76
21	5389.92
22	6492.96
23	7757.28
24	9195.84
25	10827.36
26	12666.24
27	14731.2
28	17036.64
29	19604.16
30	22452.48

# **Torque & Inertia Values**

-			
Model	Tc	t	lc
CB-2	1.65	0.003	0.0116
CB-4	6.60	0.004	0.0450
CB-5	6.88	0.004	0.1663
CB-6	8.75	0.005	1.22
CB-8	20	0.005	8.1
CB-10	50	0.006	30

# **Application Engineering**

# **Selection Considerations**

# 3. Determine clutch or brake torque value

With the inertia value calculated in Step 2, determine the torque requirement for the function determined in Step 1.

# A) For Overrunning and Start-Stop (random start-stop) (WSC Models SS and 0)

 $T = WR^2 \times RPM + friction torque$ 3700 x t

### Where-

T = Torque required from wrap spring  $WR^2$  = load inertia (Step 2) RPM = shaft speed at clutch location t = time to engagement (.003 for clutch)

# B) For single revolution applications (CB and WSC Model S)

$$T = WR^2 \times RPM - friction torque^*$$

### Where-

T = torque required from wrap spring WR<sup>2</sup> = Load inertia (Step 2)

RPM = Shaft speed at clutch or brake location

t = time to disengagement (.0015 for brake)

Find the value of T on the Torque vs. Model Comparison Chart on page 36.

\*Frictional (drag) torque is the torque necessary to overcome static friction. It may be measured by a spring-scale or by dead-weights, applied to a known moment arm so gradually as to make inertia negligible. It is that torque found just sufficient to induce motion.

# 4. Verify selection with unit inertia

From the individual product specifications find the unit inertia of the model selected in Step 3. Add this to the load inertia previously determined to arrive at the total torque requirement.

# A) For Overrunning and On-Off (WSC Models SS and 0)

A) 
$$T_t = \frac{(WR_{LOAD}^2 + WR_{UNIT}^2)RPM}{3700 \times t} + friction torque$$

# B) For Single Revolution Start-Stop (CB, Super CB and WSC Model S)

B) 
$$T_t = \frac{(WR^2_{LOAD} + WR^2_{UNIT})RPM}{3700 \times t}$$
 - friction torque

Where– $T_t$  = total system torque (WR<sup>2</sup><sub>LOAD</sub>) = load inertia (WR<sup>2</sup><sub>UNIT</sub>) = clutch inertia

Find this new torque value on the Torque vs. Model Comparison Chart on page 36 to verify the model selected in Step 3.

# Minimum Load Inertia— Super CB and CB Clutch/Brakes

In order to achieve the CB accuracy capability of  $\pm 1/2^{\circ}$ , a minimum load inertia is required to fully engage the brake spring and disengage the clutch spring. This minimum inertia (I) can be calculated from the accompanying formula and chart:

$$I = \frac{\text{(t) } (T_c + T_o) (3700)}{\text{BPM}} - I_c$$

I = Minimum inertia required to fully activate the clutch/brake—lb.in.<sup>2</sup>

t = Time - Seconds

T<sub>c</sub> = Torque required to fully activate the clutch/brake—in.lb.

 $T_0 = \text{Drag torque} - \text{in.lb.}$ 

RPM = Revolutions per minute

 $I_c$  = Inertia at the output side of the clutch — Ib.in.<sup>2</sup>

**Example:** CB-6 in a system running at 200 RPM with ¾" bore and 20 in.lb. drag. What inertia is required to fully activate the clutch/brake?

$$I = \frac{(0.005) (8.75 + 20) (3700)}{(200)} - 1.221 = 1.438 \text{ lb.in.}^2$$

**Note:** When calculated inertia is zero or negative, no further action is required. If the calculation result is positive, additional inertia equal to or exceeding the result should be added.

# How to determine maximum inertia load of CBs

$$\frac{T \times 3700 \times t}{RPM} = WR^2$$

$$T = Clutch Torque$$

$$t = .0015$$

# **Part Numbers**

Bore	Voltore	Dototion		Stops	4	Bore	Voltere	Dotation	Innut		Stops	4
		Rotation	1	2	4	Size	Voltage	MOTERIO	input	1	2	4
CB-2	2					SCB.	-8					
0.25"	24 VDC	CCW CCW	302-17-001 302-27-001	302-17-002 302-27-011	302-17-003 302-27-003	1.25"	24 VDC	CCW		328-17-019 328-27-019	328-17-020 328-27-020	328-17-02 <sup>-</sup> 328-27-02 <sup>-</sup>
0.25"	115 VAC	CCW CCW	302-17-007 302-27-007	302-17-008 302-27-008	302-17-009 302-27-009	1.25"	115 VAC	CCW		328-17-043 328-27-043	328-17-044 328-27-044	328-17-045 328-27-045
CB-4	,					1.5"	24 VDC	CW CCW		328-17-013 328-27-013	328-17-014 328-27-014	328-17-015 328-27-015
0.375"	24 VDC	CCW	304-17-001 304-27-001	304-17-011 304-27-007	304-17-007 304-27-026	1.5"	115 VAC	CCW		328-17-037 328-27-037	328-17-038 328-27-038	328-17-039 328-27-039
0.375"	115 VAC	CCW	304-17-003 304-27-003	304-17-008 304-27-015	304-17-018 304-27-025	WSC	<b>;-2</b>					
CB-5						0.25" 0.25"	S S	CCW	Hub Hub	202-10-016 202-20-016	202-10-009 202-20-015	202-10-020 202-20-017
0.5"	24 VDC	CCW	305-17-001 305-27-001	305-17-002 305-27-002	305-17-003 305-27-003	0.25" 0.25"	S S	CW CCW	Shaft Shaft	202-30-011 202-40-014	202-30-007 202-40-008	202-30-015 202-40-017
0.5"	115 VAC	CCW	305-17-007 305-27-007	305-17-008 305-27-008	305-17-009 305-27-009	WSC	<b>;-4</b>					
CB-6	;					0.375" 0.375"	S S	CCW	Hub Hub	204-10-001 204-20-004	204-10-016 204-20-008	204-10-010 204-20-010
0.75"	24 VDC	CCW	306-17-051 306-27-029	306-17-074 306-27-046	306-17-162 306-27-134	0.375" 0.375"	S S	CCW	Shaft Shaft	204-30-001 204-40-001	204-30-007 204-40-006	204-30-009 204-40-012
0.75"	115 VAC	CCW CCW	306-17-053 306-27-031	306-17-060 306-27-039	306-17-073 306-27-045	WSC	-5					
1.0"	24 VDC	CCW	306-17-057 306-27-032	306-17-061 306-27-147	306-17-031 306-27-150	0.5" 0.5"	S S	CCW	Hub Hub	205-10-001 205-20-001	205-10-014 205-20-006	205-10-017 205-20-01
1.0"	115 VAC	CCW CCW	306-17-059 306-27-034	306-17-062 306-27-044	306-17-075 306-27-037	0.5" 0.5"	S S	CW CCW	Shaft Shaft	205-30-001 205-40-004	205-30-014 205-40-007	205-30-016 205-40-016
CB-8	}					WSC	<b>6-6</b>					
1.25"	24 VDC	CCW CCW	308-17-101 308-27-101	308-17-102 308-27-102	308-17-103 308-27-103	0.75" 0.75"	S S	CCW	Hub Hub	206-10-002 206-20-002	206-10-062 206-20-023	206-10-06 <sup>2</sup> 206-20-058
1.25"	115 VAC	CCW CCW	308-17-107 308-27-107	308-17-108 308-27-108	308-17-109 308-27-109	0.75" 0.75"	S S	CCW CCW	Shaft Shaft	206-30-011 206-40-002	206-30-052 206-40-014	206-30-020 206-40-020
1.5"	24 VDC	CW CCW	308-17-119 308-27-119	308-17-120 308-27-120	308-17-121 308-27-121	1.0" 1.0"	S S	CW CCW	Hub Hub	206-10-003 206-20-003	206-10-057 206-20-060	206-10-059 206-20-013
1.5"	115 VAC	CW CCW	308-17-125 308-27-125	308-17-126 308-27-126	308-17-127 308-27-127	1.0" 1.0"	S S	CCW	Shaft Shaft	206-30-003 206-40-013	206-30-051 206-40-023	206-30-056 206-40-025
SCB-	5					WSC	8-8					
0.5"	24 VDC	CW CCW	325-17-001 325-27-001	325-17-002 325-27-002	325-17-003 325-27-003	1.25" 1.25"	S S	CCW	Hub Hub	208-10-004 208-20-001	208-10-027 208-20-028	208-10-028 208-20-030
0.5"	115 VAC	CW	325-17-004 325-27-004	325-17-005 325-27-005	325-17-006 325-27-006	1.25" 1.25"	S S	CW	Shaft Shaft	208-30-001 208-40-013	208-30-021 208-40-015	<u> </u>
SCB-	6					1.50" 1.50"	S S	CW	Hub Hub	208-10-007 208-20-003	208-10-025 208-20-032	208-10-030 208-20-021
0.75"	24 VDC	CW CCW	326-17-007 326-27-007	326-17-008 326-27-008	326-17-009 326-27-009	1.50" 1.50"	S S	CW	Shaft Shaft	208-30-003 208-40-003	208-30-025 208-40-020	208-30-027 208-40-022
0.75"	115 VAC	CW	326-17-019 326-27-019	326-17-020 326-27-020	326-17-021 326-27-021			Series uni	ts, these a	re the most commo	only requested par	ts – other
1.0"	24 VDC	CW	326-17-010 326-27-010	326-17-011 326-27-011	326-17-012 326-27-012	For th		ies, other	units offeri	, bores and stop on ng different bores,		
1 0"	115 VAC	CW	326-17-022	326-17-023	326-17-024	10 311	oporaciói	i aio avalla	2010.			

Control Part #'s

115 VAC

1.0"

One Shot, 150 Ohms 901-00-014 One Shot, Octal Socket 901-00-019

CW

CCW

326-17-022

326-27-022

326-17-023

326-27-023

326-17-024

326-27-024

# **CB Metric Part Numbers**

Bore				Stops	
Size \	/oltage	Rotation	1	2	4
CB-2					
6mm	24 VDC	CW CCW	312-17-001 312-27-001	312-17-002 312-27-002	312-17-003 312-27-003
CB-4					
10mm	24 VDC	CW CCW	314-17-001 314-27-001	314-17-002 314-27-002	314-17-003 314-27-003
CB-5					
12mm	24 VDC	CW CCW	315-17-001 315-27-001	315-17-002 315-27-002	315-17-003 315-27-003
CB-6					
20mm	24 VDC	CW CCW	316-17-001 316-27-001	316-17-003 316-27-003	316-17-005 316-27-005
25mm	24 VDC	CW CCW	316-17-002 316-27-002	316-17-004 316-27-004	316-17-006 316-27-006
CB-8					
35mm	24 VDC	CW CCW	318-17-001 318-27-001	318-17-003 318-27-003	318-17-005 318-27-005
40mm	24 VDC	CW CCW	318-17-002 318-27-002	318-17-004 318-27-004	318-17-006 318-27-006

				01	
Bore Size	Voltage	Rotation	1	Stops 2	4
SIZE	Voltage	notation	'		-
CB-1	10				
40mm	24 VDC	CW	310-17-001	310-17-003	310-17-005
		CCW	310-27-001	310-27-003	310-27-005
SCB	-5				
12mm	24 VDC	CW	335-17-001	335-17-002	335-17-003
		CCW	335-27-001	335-27-002	335-27-003
SCB	-6				
20mm	24 VDC	CW	336-17-013	336-17-014	336-17-015
		CCW	336-27-013	336-27-014	336-27-015
25mm	24 VDC	CW	336-17-016	336-17-017	336-17-018
		CCW	336-27-016	336-27-017	336-27-018
SCB	-8				
35mm	24 VDC	CW	338-17-013	338-17-014	338-17-015
		CCW	338-27-013	338-27-014	338-27-015
40mm	24 VDC	CW	338-17-016	338-17-017	338-17-018
		CCW	338-27-016	338-27-017	338-27-018
SCB	-10				
40mm	24 VDC	CW	330-17-001	330-17-003	330-17-005
		CCW	330-27-001	330-27-003	330-27-005

# **CB Metric Part Numbers**

Model	Voltage	Coil	Solenoid Kit*
CB-2	115 VAC	002-1204	-
	24 VDC	002-1201	-
	90 VDC	002-1203	-
	12 VDC	002-1202	-
CB-4 / CB-5 / SCB-5	115 VAC 24 VDC 90 VDC 12 VDC 220 VAC (50/60HZ)	275-1-0166 275-1-0163 275-1-0165 275-1-0162 275-1-0168	= = =
CB-6 / SCB-6 / CB-8	115 VAC	275-1-0501	101-1-0058
	24 VDC	275-1-0103	101-1-0028
	90 VDC	275-1-0105	101-1-0030
	12 VDC	275-1-0102	101-1-0027
	220 VAC (50/60HZ)	275-1-0504	101-1-0061
SCB-8	115 VAC	275-1-0501	101-1-0058
	24 VDC	275-1-0073	101-1-0053
	90 VDC	275-1-0074	101-1-0055
	12 VDC	275-1-0072	101-1-0052
	220 VAC (50/60HZ)	275-1-0504	101-1-0061
CB-10 / SCB-10	115 VAC (CW)**	275-1-0579	-
	115 VAC (CCW)**	275-1-0580	-
	24 VDC	275-1-0073	-
	90 VDC	275-1-0074	-
	12 VDC	275-1-0072	-

<sup>\*</sup> Solenoid kit includes coil, plunger, return spring, solenoid plate, plunger guide and mounting hardware \*\* Includes laminated body and stack - newer design not compatable with older units

# **Application Data Form**

# Mail or Fax to:

# **Warner Electric**

Technical Support

449 Gardner Street, South Beloit, Illinois 61080

Phone 815-389-3771 • Fax 815-389-2582 • www.warnerelectric.com

Email: techsupport@warnerelectric.com

Actuation  Mechanical Electrical Voltage	( ) ( ) AC DC	Technical Data         Speed
Motion Single Revolution Fractional Revolution Angle	( ) ( ) ( )	Cycle Rate ( per second ) Life Expectancy (hrs or cycles )  Environmental Consideration
Accuracy Start Stop	( ms ) ( ± <u>    °</u> )	
Shaft Diameter  Minimum  Maximum	( ")	

# **Describe the application function**



# Altra Industrial Motion

### **Warner Electric Facilities**

### **North America**

31 Industrial Park Road New Hartford, CT 06057 - USA 860-379-1252

Electromagnetic Clutches and Brakes

449 Gardner Street South Beloit, IL 61080 - USA 815-389-3771

4578 East Park 30 Drive Columbia City, IN 46725 - USA 260-244-6183

Precision Electric Coils and Electromagnetic Clutches and

**Customer Service** 1-800-825-6544

For Application Support

1-800-825-9050

### Europe

7, rue Champfleur, B.P. 20095 St Barthelemy d'Anjou - France +33 (0)2 41 21 24 24 Electromagnetic Clutches and Brakes

**Customer Service** +33 (0)2 41 21 24 76

For Application Support +33 (0) 2 41 21 24 24

### **Asia Pacific**

Australia +61 2 9894 0133

+86 21 5169-9255

Hong Kong +852 2615 9313

Singapore +65 6487 4464

Taiwan

+886 2 2577 8156

Thailand

+66 2322 5527

### The Brands of Altra Industrial Motion

### **Couplings**

Ameridrives www.ameridrives.com

**Bibby Turboflex** www.bibbyturboflex.com

**Guardian Couplings** www.guardiancouplings.com

Huco

www.huco.com

**Lamiflex Couplings** www.lamiflexcouplings.com

Stromag

www.stromag.com

TB Wood's

**Geared Cam Limit Switches** 

Stromag

www.stromag.com

## **Electric Clutches & Brakes**

**Inertia Dynamics** 

Matrix

www.matrix-international.com

Stromag

www.stromag.com

Warner Electric

www.warnerelectric.com

**Linear Products** 

Warner Linear www.warnerlinear.com

**Engineered Bearing Assemblies** 

Kilian

www.kilianbearings.com

# **Heavy Duty Clutches & Brakes**

**Industrial Clutch** www.indclutch.com

Twiflex

www.twiflex.com

Stromag

www.stromag.com

**Svendborg Brakes** 

www.svendborg-brakes.com

Wichita Clutch

www.wichitaclutch.com

### **Belted Drives**

TB Wood's

www.tbwoods.com

### Gearing

**Bauer Gear Motor** www.bauergears.com

**Boston Gear** 

www.bostongear.com

**Delroyd Worm Gear** www.delroyd.com

**Nuttall Gear** 

www.nuttallgear.com

# **Overrunning Clutches**

Formsprag Clutch www.formsprag.com

**Marland Clutch** 

www.marland.com

Stieber

www.stieberclutch.com

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